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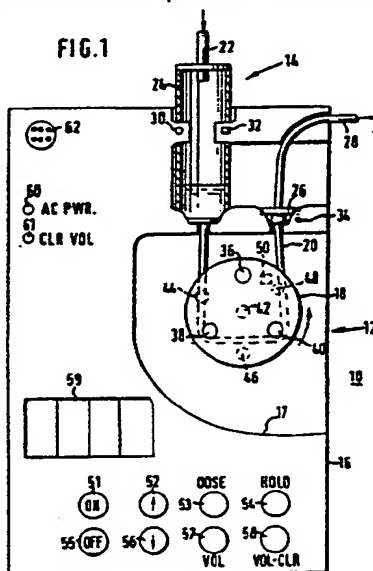
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(54) Motor unit for a fluid pump and method of operation.

(57) An enteral nutrition pump system (10) operates in a cyclical manner with a period between cycles being selected in accordance with the desired fluid delivery rate. Each pump cycle may correspond to a single rotation of the rotor (18) or a fractional rotation of the rotor. Rotor rotation may alternatively be sensed by utilization of magnetic sensors (50) or by monitoring of the AC component of current supplied to a DC motor driving the rotor.

FIG.1



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MOTOR UNIT FOR A FLUID PUMP AND METHOD OF OPERATION

This invention relates to pumps for delivering medical fluids and particularly relates to peristaltic pumps for delivery of enteral nutrition fluids to a patient.

In accordance with known techniques the delivery of enteral nutrition fluids to a patient can be accurately controlled as to volumetric delivery rate by the use of a delivery system which includes a motor unit and a disposable delivery set. Likewise similar systems may be used for pumping of other fluids for medical purposes, such as intravenous infusion, blood pumping or supply of measured volumes of liquid medication to pre-loaded syringes or other containers.

In known systems for delivering enteral fluids the rate of fluid delivery is controlled by regulating the speed of a pump motor in accordance with the desired volume rate. Pump motor speed may be controlled, for example, by providing pulses to a stepper motor. Another system for providing variable rate fluid delivery makes use of a peristaltic pump with variable tension on the pump tube in combination with a constant speed motor.

In other known systems for pumping medical fluids there are provided means for monitoring rotation of the pump rotor, for example, by magnetic detection or by optical rotation detectors. In such systems the actual rotation rate of the motor is compared to the desired rotation rate for purposes of making corrections to the rotation rate of the motor. Alternately the motor may be operated to rotate the pump by a number of rotations corresponding to the desired volume.

It is an object of the present invention to provide a new and improved method for regulating the volumetric rate of fluid delivery in a medical fluid delivery system and to provide apparatus for carrying out the improved method.

In accordance with the present invention there is provided a motor unit for a medical fluid delivery system for use with a disposable delivery set for pumping medical fluid, characterised in that it comprises: pump operating means, including a motor, for acting in cooperation with the delivery set to deliver a volume of the fluid during each operating cycle;

and pump control means for controlling the pump operating means to deliver the fluid at a desired volumetric rate, the pump control means including means responsive to signals indicating the desired rate for activating the pump operating means for one of the operating cycles and for repeating the activation at variable time intervals selected in accordance with the desired volumetric rate.

In accordance with a preferred embodiment of the invention the pump operating means is a pump rotor for operating in connection with a pump tube on the delivery set to form a peristaltic pump and the pump operating cycle comprises a selected angular rotation of the pump rotor. In one arrangement the pump control means includes means for sensing the condition of the pump operating means with respect to an operating cycle, and the sensing means comprise a magnet and a magnetic field sensor. In another arrangement the sensing means may detect the AC component of the current supplied to a DC motor.

The medical fluid delivery system which comprises the novel motor unit and a disposable fluid delivery set carries out a novel method for controlling the rate of fluid delivery. The novel method includes providing means for detecting the completion of an operating cycle of the pump operating means and operating the motor unit until the completion of the operating cycle is detected. Operation of the motor unit is repeated at variable time intervals which are selected in accordance with the desired rate of fluid delivery.

In accordance with another aspect of the present invention the AC component of the DC motor current is detected and compared to a reference level in order to detect the current variation which results from the presence of a pump tube on the rotor. Accordingly, any mis-installation of the pump tube will be detected by the fluid delivery pump.

For a better understanding of the present invention, together with other and further objects, reference is made to the following description, taken in conjunction with the accompanying drawings, in which:

Figure 1 is a plan elevation view of an enteral fluid delivery system incorporating the present invention.

Figure 2 (comprising Figures 2a, 2b and 2c) is a circuit diagram for the system of Figure 1.

Figure 3 is a circuit diagram for a portion of a modified delivery system in accordance with the present invention.

Figure 4 is a timing diagram illustrating signals utilized in the present invention.

Figure 1 is an illustration of an enteral fluid delivery system incorporating a motor unit in accordance with the present invention. The enteral delivery system 10 includes a motor unit 12 and a disposable delivery set generally indicated as 14 which is arranged to be mounted on the motor unit. The motor unit 12

includes a housing 16, which in the illustrated embodiment includes a recess 17 within which a rotor 18 is mounted. Rotor 18 is driven by a conventional constant speed DC motor which drives shaft 42. The delivery set 14 includes a pump tube 20, made of flexible plastic which surrounds rotor 18 and interacts with 3 rollers 36, 38 and 40 mounted on rotor 18 to form a peristaltic pump. Rotation of the rotor 18 in the direction indicated by the arrow in Figure 1 causes the rollers 36, 38 and 40 to interact with pump tube 20 and pump fluid through the tube at a rate which is determined by the rate rotation of rotor 18.

Delivery set 14 includes an inlet tube 22, which is connected to a supply of enteral fluids, such as a fluid reservoir which may be mounted on an IV pole above the motor unit 12. The inlet tube 22 is connected to drip chamber 24 which is mounted to a recess on housing 16 and secured to one end of pump tube 20. The outlet end of pump tube 20 is provided with a mounting member 26 which is received in another recess on housing 16 to thereby secure the outlet end of tube 20. A fluid delivery tube 28 is connected to mounting member 26 and supplies fluid pumped by the system to an enteral feeding tube connected to a patient or to another medical fluid delivery system.

The system illustrated in Figure 1 additionally includes a light source 30 and a light detector 32 for operation in connection with drip chamber 24 to detect the occurrence of drops in the drip chamber which pass between light source 30 and detector 32 in a manner which is known in the art. Mounting member 26 includes magnetized material, the presence of which can be detected by magnetic field detector 34.

The motor unit 12 includes control buttons 51 through 58 for operating the unit to turn it on or off, to set the dose or volume rate of fluid delivery by the pump, to interrupt operation of the pump and to increase or decrease the designated fluid volume or volume rate. A four digit alphanumeric segment display 59 is provided for indicating the selected fluid delivery rate or delivered volume and for providing alarm messages or codes. Light emitting diode 60 and 61 are provided for indicating that the unit is plugged into AC power or indicating that the volume setting has been cleared. An enunciator 62 is provided for signalling an audible alarm to indicate, for example, that the pump has completed delivering a designated volume of fluid.

Housing 16 is provided with a magnetic field sensor 50 which is arranged adjacent and behind rotor 18 in order to detect the magnetic field provided by magnets 44, 46 and 48 which are mounted on rotor 18. The presence of the magnets 44, 46 and 48 is detected as the magnets pass sensor 50 during rotation of rotor 18.

Figure 2 is a schematic diagram of the circuits in the pump motor unit 12 of Figure 1. The schematic representations of the various components of Figure 1 have been given same reference numerals in Figure 2.

The motor unit operates under the control of a microcomputer 64 which is provided with a control program which is set forth in Appendix I. A programmable interval timer 68 is provided for operating and initiating microcomputer 64. A clock 66, operating at 2 Mhz, provides clock pulses to the system. The various controls of the unit, 51 through 58, are provided as input signals which ground various input terminals of the microcomputer to thereby signal the operators input instructions. The alphanumeric display 59 is driven by the microcomputer as is LED indicator 61. Additional inputs to the microcomputer are provided by the magnetic field sensors 34 and 50 which sense respectively the magnetized mounting member 26 and the magnets 44, 46 and 48 on rotor 18. Likewise the drop detector 30, 32 is connected to provide input signals to the microcomputer. An AC power rectifier 72 is provided for AC operation and battery charging. Portable DC operation is available using battery 74. The AC circuit is arranged to charge the DC battery when the unit is connected to AC power. A low battery and dead battery detector circuit 70 is provided to signal the microcomputer that the battery needs recharging. The microcomputer provides an output motor signal which is coupled by transistor 80 to switching transistors 82, 84. Transistor 82 turns on the power supply to motor voltage regulator 88 when the motor is to be operated and transistor 84 short circuits the motor to lock it into position when the motor signal is no longer present. Switching transistor 78, which is provided with a power signal by transistor 76, operates to supply current to the motor system and the other electronic systems by voltage regulator 86 when power is turned on. The motor 90 is provided with a safety circuit 92 which provides a short circuit when the motor is operated for an excess period of time. The short circuit causes fuse 94 to open thereby disabling the set when continuous motor operation occurs, to avoid providing excess enteral fluid to a patient.

Unlike conventional enteral nutrition systems the system 10 of the present invention is designed to provide an intermittent motor operation with the periodicity of the intermittent operation being regulated to adjust to the desired rate of fluid delivery. The operation of the system of the present invention is therefore cyclical and will be explained with respect to timing diagrams of Figure 4. Graph A of Figure 4 illustrates the motor voltage of the enteral fluid delivery system 10. The motor voltage is turned on and operated for a time period G which is regulated by detecting the rotation of rotor 18, in the case of Graph A for one

complete revolution. With reference to Figure 1 it may be seen that during one complete revolution, represented by motor voltage period G, three magnets 44, 46 and 48 all pass magnetic field detector 50 and are sensed thereby. Curve B in Figure 4 illustrates the output signal from the rotor sensing magnetic field detector 50 which occurs during the cycle of operation indicated by motor voltage G. During an initial period of approximately .45 seconds designated F in Figure 4 the operation of the rotor sensing is inhibiting by software in microcomputer 64, so that the initial on period J of magnetic field detector 50 is not responded to by the program. Thereafter, during one complete revolution of the rotor, the signal from detector 50 goes to zero as each magnet is encountered by detector 50. Upon detection of the third magnet, at the end of period G, the motor voltage is turned off. In accordance with the preferred embodiment of the present invention the unit repeats the cyclical operation a time period I after initiation of the first operation. The time period H during which there is provided no motor voltage is permitted to be variable, since it depends on the actual time taken for rotation of the rotor and the selected interval I. The interval I is selected according to the rate of fluid delivery to be provided by the set which is set by the operator. In one embodiment of the invention period I varies from 13.5 seconds corresponding to a delivery rate of 100 milliliters per hour to 4.5 seconds corresponding to a fluid delivery rate of 300 milliliters per hour. Motor operation period G takes approximately 4 seconds but may vary according to mechanical conditions of the motor and pump tube.

Graph E in Figure 4 shows an alternate timing arrangement wherein the motor cycle consists of a single one-third of a rotation of the rotor 18. In accordance with the operation method of Graph E the motor current period G' is ended by the detection of the first of the three circumferentially arranged magnets by magnetic field sensor 50. Again the timing I between each operating cycle of the motor is varied in order to control volumetric fluid rate delivered by the pump. In the same embodiment as previously discussed a fluid rate of 1 to 100 milliliters per hour can be delivered using a cycle interval I which ranges from 450 to 4.50 seconds.

As an alternate, or in addition to providing magnets on rotor 18 for purposes of detecting completion of a motor cycle, the motor current may be monitored for purposes of determining the rotational position of the rotor 18. Figure 3 is a schematic diagram of a circuit wherein there is provided a motor current monitoring circuit 96 which includes a low resistance resistor in series with the motor the voltage across which is AC coupled to an AC amplifier 92 for purposes of monitoring the AC component of the DC motor current. Graph C of Figure 4 illustrates a typical motor current for the operating cycle of Graph A of Figure 4. The motor current initially rises to a high level for purposes of overcoming the starting resistance and accelerating rotor 18 to its normal velocity. Thereafter the motor current drops but reaches periodic peaks corresponding to the resistance of rollers 36, 38 and 40 as they stretch pump tube 20 to its furthest position. The peak periods of motor current, which are illustrated as negative going pulses in the digitized signal of curve D, which is the output at point 96 of the circuit of Figure 3, may be used for purposes of detecting rotor position and may be used also for assuring that the pump tube 20 is properly mounted to rotor 18. Because of the initially high rotor current, which results from starting up the rotor, the current sensing is software inhibited for time period K of approximately .25 seconds prior to initiating the threshold detection which results in the pulses of curve D. Each of the pulses illustrated in curve D, which are negative going, have a positive going pulse which occurs a time period L prior to the end of a motor cycle, there being three such pulses during one rotation of the rotor. Accordingly, the curve D signal can be used for purposes of detecting and monitoring rotation position of rotor 18, and thereby indicating to the motor control circuit the completion of an operating cycle. As an alternate to providing delay L after the end of the curve D pulses, the motor cycle may be arranged to end at the end of the pulse, providing a different rotor position between cycles.

The motor current monitoring previously described can additionally be used in cases wherein the motor voltage is provided only for a one-third rotation of the rotor as discussed with respect to curve E.

An additional use of the motor current monitoring circuit, which provides the signal of curve D of Figure 4 is to provide assurance to the system that the pump tube 20 has been properly mounted on rotor 18. Accordingly at the initiation of motor current and after a delay period K a flag can be set by the microprocessor which is cleared by the negative going pulse of curve D to indicate proper pump tube positioning. The flag would be reset at the start of each operating cycle or may also be reset on the occurrence of the one-third rotation of the rotor sensing current shown by curve B. If the flag is not cleared by the negative going pulse of curve D there is an indication that either there is no pump tube or that the pump tube has been improperly mounted and an alarm signal can be initiated.

Claims

1. A motor unit for a medical fluid delivery system for use with a disposable delivery set for pumping medical fluid, characterised in that it comprises:
 - 5 pump operating means, including a motor, for acting in cooperation with the delivery set (14) to deliver a volume of the fluid during each operating cycle;
 - and pump control means for controlling the pump operating means to deliver the fluid at a desired volumetric rate, the pump control means including means responsive to signals indicating the desired rate for activating the pump operating means for one of the operating cycles and for repeating the activation at
 - 10 variable time intervals selected in accordance with the desired volumetric rate.
2. A motor unit as claimed in claim 1 wherein the pump operating means comprises a pump motor (18) for acting in cooperation with a pump tube (20) on the delivery set (14) and wherein the operating cycle comprises a selected angular rotation of the pump rotor.
3. A motor unit as claimed in claim 1 or 2 wherein the pump control means includes means for sensing
 - 15 the condition of the pump operating means with respect to the operating cycle.
4. A motor unit as claimed in claim 3 wherein the means for sensing comprises at least one magnet (44, 46, 48) and a magnetic field sensor (50).
5. A motor unit as claimed in claim 3 wherein the pump operating means comprises a DC motor and wherein the means for sensing the condition of the pump operating means comprises means for sending
 - 20 the AC component of the current supplied to the DC motor.
6. A motor unit for a medical fluid delivery system for use with a disposable delivery set having a flexible pump tube for engagement with the motor unit for pumping medical fluids, characterised in that it comprises:
 - a housing (16) for receiving at least portions of the delivery set (14);
 - 25 a motor driven rotor (18) mounted on the housing (16) for rotational movement with respect thereto and for receiving the flexible pump tube (20) for forming a peristaltic pump;
 - at least one magnet (44, 46, 48) and at least one magnetic field detector (50) mounted to the rotor (18) and the housing (16) for relative rotational motion with respect to each other, the magnet and the magnetic field detector being operatively adjacent to each other at at least one rotational position of the rotor;
 - 30 and pump control means, responsive to selection of a fluid delivery rate and responsive to the magnetic field detector (50), for operating the motor until the rotor is in the rotation position with the magnet and the magnetic field detector adjacent each other and for repeating the operation at variable time intervals selected in accordance with the selected fluid delivery rate.
7. A motor unit for a medical fluid delivery system for use with a disposable delivery set having a
 - 35 flexible pump tube for engagement with the motor unit for pumping medical fluids, characterised in that it comprises:
 - a housing for receiving at least portions of the delivery set;
 - a rotor driven by a DC motor, mounted on the housing for rotational motion with respect thereto and for receiving the flexible pump tube for forming a peristaltic pump;
 - 40 means for sensing the AC component of the current supplied to the DC motor thereby to sense rotation of the rotor by an incremental amount corresponding to an incremental volume of pumped fluid;
 - and pump control means, responsive to selection of a fluid delivery rate and responsive to the current sensing means, for operating the motor until the incremental rotation is sensed and for repeating the operation at variable time intervals selected in accordance with the selected fluid delivery rate.
- 45 8. A method for controlling the rate of fluid delivery in a medical fluid delivery system comprising a motor unit and a disposable fluid delivery set for mounting to the motor unit to form a pump, and wherein the motor unit is adapted to act on the fluid delivery set in repeated operating cycles to deliver a volume of fluid for each cycle and means are provided for detecting the completion of the operating cycle, which method comprises:
 - 50 operating the motor unit until the completion of the operating cycle is detected;
 - and repeating operation of the motor unit at time intervals selected in accordance with the desired rate of fluid delivery.
9. A method as claimed in claim 8 for further controlling the volume of fluid delivered comprising counting the number of the operating cycles and interrupting the repeating operation when a number of the
 - 55 operating cycles corresponding to a desired volume has been completed.
10. A method for controlling the rate of fluid delivery by a fluid delivery system comprising a motor unit and a disposable delivery set, wherein the pump unit includes a motor driven rotor for engaging a flexible pump tube on the delivery set to form a peristaltic pump and wherein at least one magnet is provided on

the rotor and a magnetic field detector is provided on the pump unit at a position adjacent the magnet in one rotational position of the rotor, which method comprises:
operating the pump unit to rotate the rotor until the magnetic field detector detects the magnet; and
repeating the operating step at a variable time interval selected according to the desired delivery rate of the
5 delivery system.

11. A method as claimed in claim 10 wherein there are provided a plurality of the magnets equally angularly spaced on the rotor and wherein the operating step comprises operating the pump unit until the magnetic field detector detects a selected number of the magnets.

12. A method as claimed in claim 10 or 11 wherein the operating step further includes the step of
10 inhibiting operation of the magnetic field detector for a selected time.

13. A method for controlling the rate of fluid delivery by a fluid delivery system comprising a motor unit and a disposable delivery set, wherein the pump unit includes a rotor driven by a DC motor for engaging a flexible pump tube on the delivery set to form a peristaltic pump, which method comprises:

15 detecting the AC component of the DC current and forming digital pulses representative thereof;
operating the pump unit to rotate the rotor until a selected number of the digital pulses occur; and
repeating the operating step at a time interval selected according to the desired delivery rate of the delivery system.

14. A method as claimed in claim 13 wherein the operating step further includes a step of inhibiting the AC detecting step for a selected time.

20 15. A method for detecting the absence of a pump tube on the rotor in a fluid delivery system comprising a motor unit and a disposable delivery set, wherein the pump unit includes a DC motor driven rotor for engaging a flexible pump tube on the delivery set to form a peristaltic pump, which method comprises:

25 detecting the AC component of the current provided to the DC motor;
comparing the detected AC component of the current to a reference level thereby to detect current variation resulting from the presence of a pump tube on the rotor.

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6-7593

APPENDIX I

Avocet 6805 Assembler v1.12, #01040 Chip=6305 12/18/87 16:08:57
K224/324 PUMP

```

1 $CHIP(6305)
2 $pagewidth=132
3 $PAGINATE
4 $TITLE(K224/324 PUMP)
5 $XREF
6 ;
7 ;
8 ; This file contains the software for the K224/K324 series of
9 ; Enteral Feeding Pumps. It is based on COMBO2.ASM a combined
10 ; F1500 and K224 program. See COMBO2.ASM for revision history.
11 ;
12 ;
13 ; FILE NAME= KPMP31.ASM
14 ;
15 ; DATE | REVISION | DESCRIPTION

```

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16 ;-----
17 ;
18 ; 12/04/87 | 031.0 | DISPLAY LEADING ZERO'S IN DOSE MODE.
19 ; | | CHECK FOR DROPS CONTINUOUSLY IN RUN MODE
20 ; | | WHEN RATE IS < 100 ML/HR.
21 ;-----
22 ;
23 ; 11/24/87 | 030.0 | ADD NOPS TO IR TEST DURING TESTD.
24 ; | | CLEAR TESTD FLAG WHEN OFF MODE IS ENTERED TO
25 ; | | ALLOW PUMP TO DISABLE IF NECESSARY.
26 ; | | CLEAR VOL MODE FLAG WHEN LO BAT IS ENTERED
27 ; | | LOCK-OUT HOLD/START AND VOL BUTTONS WHEN
28 ; | | INC OR DEC BUTTONS ARE PRESSED.
29 ; | | FIX CLR VOL LED ERROR
30 ; | | CHECK DEC BUTTON BEFORE INC BUTTON.
31 ; | | ADD DELAY TO INC AND DEC BUTTON IN DOSE MODE TO
32 ; | | ALLOW TIME FOR DOSE DISPLAY.
33 ;-----
34 ;
35 ; 11/11/87 | 029.0 | CHANGE PUMP ID FROM PORTD(1), TO PORTB(6).
36 ;-----
37 ;

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38 ; 10/23/87 | 028.0 | FIXED 24 HOUR TIME ERROR. PUMP WAS TIMING 21 HOURS
39 ; | | MODIFIED SO THAT PUMP DISABLES AFTER 24 HOURS
40 ; | | WHEN ON AC OR BATTERY POWER.
41 ; -----
42 ;
43 ; 10/16/87 | 027.0 | CHANGED SEICK ROUTINE TO TEST FOR SET WHENEVER
44 ; | | PUMP IS IN RUN MODE. OLD VERSION ONLY CHECKED
45 ; | | WHEN MOTOR IS RUNNING.
46 ; | | RATE CHECK FOR 324 IS DISABLED DURING TEST MODE.
47 ; | | DISABLE DOSE BUTTON WHILE INC OR DEC BUTTONS
48 ; | | ARE PRESSED.
49 ; -----
50 ;
51 ; 10/13/87 | 026.0 | ADD RECHECK OF PUMP ID DURING TESTD
52 ; | | ADDED DELAY FROM MOTOR TURN-ON TO DEAD BAT ROUTINE
53 ; | | CHANGED LOW BAT ROUTINE SO IT KILLS POWER IF
54 ; | | LO BAT OCCURS WHEN UNIT IS ALREADY OFF.
55 ; | | CHANGE POLARITY OF AC DETECT LINE. (REV 7 BOARD)
56 ; -----
57 ;
58 ; 10/13/87 | 025.0 | CORRECTED ERROR IN 1/2 SEC TIMER..
59 ; | | ADDED DOSE DEL CHECK PRIOR TO RUN MODE

```

```

60 ;-----
61 ;
62 ; 10/12/87 | 024.0 | ADD NOPS IN DROPCK BETWEEN IR TURN-ON AND
63 ; | | TEST TO ALLOW FOR SETTLING.
64 ; | | SHORTED IR ON TIME.
65 ; | | MOVE DROPCK FROM 8 MS TO 2 MS TO IMPROVE
66 ; | | DROP DETECTION.
67 ;-----
68 ;
69 ; 10/10/87 | 023.0 | DEL STOP INSTR. FROM EACH DISABLE ROUTINE.
70 ; | | BLANK ALL DIGITS IN EACH DISABLE ROUTINE.
71 ;-----
72 ;
73 ; 10/07/87 | 022.0 | THE RESET ROUTINE HAS BEEN MODIFIED TO KEEP
74 ; | | THE PUMP OFF. TURN-ON IS NOW ACCOMPLISHED IN
75 ; | | THE INT ROUTINE. CHANGE WAS MADE TO PREVENT STRAY
76 ; | | RESEST SIGNALS FROM WATCHDOG FROM ACCIDENTLY
77 ; | | TURNING PUMP ON DURING DISABLE SEQUENCE.
78 ;-----
79 ; 9/29/87 | 021.0 | REVISED THE DISABLE ROUTINES TO DISABLE INT
80 ; | | AND LOOP UNTIL POWER DISSIPATES.
81 ;-----

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82 ;
83 ; 9/22/87 | 020.0 | TEST ROUTINE HAS BEEN ADDED. IT IS INITIATED BY
84 ; | | PRESSING THE OFF AND HOLD BUTTONS DOWN AT THE
85 ; | | SAME TIME FOR APPROX. 3 SEC WHEN PUMP IS OFF.
86 ;
87 ; 9/22/87 | 019.0 | MOTOR CONTROL SIGNAL POLARITY HAS BEEN REVERSED
88 ; | | AND TEST MODE WAS CHANGED SO THAT CLR VOL LED
89 ; | | IS TURNED OFF WHEN BUZZER IS.
90 ;
91 ; 9/08/87 | 018.0 | THE INCREMENT AND DECREMENT KEYS HAVE BEEN
92 ; | | REVERSED TO COMPENSATE FOR PC BOARD R4.
93 ; -----
94 ;
95 ; 9/03/87 | 017.0 | THIS PROGRAM HAS BEEN MODIFIED TO RUN ON A 2 MHZ
96 ; | | CLOCK.
97 ; | | THE LOW BAT TIME HAS BEEN SET TO 15 MIN.
98 ; -----
99 ; -----
100 ;
101 ; 8/28/87 | 016.0 | THE CLEAR DOSE FEATURE HAS BEEN DELETED
102 ; -----
103 ;

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104 ; 8/28/87 | 015.0 | THE HOLD ROUTINE HAS BEEN MODIFIED TO OCCUR
105 ; | | 2 1/2 MIN FROM LAST BUTTON PRESSED.
106 ; | | A WAIT STATEMENT HAS BEEN ADDED TO THE MAIN LOOP
107 ; | | AND OFF LOOP ROUTINES.
108 ; -----
109 ; 8/21/87 | 014.0 | THIS VERSION HAS BEEN MODIFIED TO ACCOMADATE
110 ; | | THE NEW ENCODED ROTARY SWITCH.
111 ; | | THE HOLD AND INCREMENT BUTTIONS HAVE BEEN SWITCHED
112 ; | | TO SIMPLIFY THE RATE KNOB DECODE OPERATION.
113 ; -----
114 ;
115 ; 8/12/87 | 013.0 | THIS VERSION HAS BEEN REDUCED BY CONVERTING
116 ; | | THE RATE INCREMENT ROUTINES TO BINARY WITH
117 ; | | DECIMAL ADJUST ADDING.
118 ; -----
119 ;
120 ; 8/05/87 | 012.0 | BLINK SUBROUTINE WAS MODIFIED SO THAT ONLY 3
121 ; | | DIGITS ARE ACTIVE WHEN PUMP IS 224.
122 ; -----
123 ;
124 ; 7/30/87 | 011.0 | MODIFIED SO THAT VOLUME AND DOSE CAN BE CLEARED
125 ; | | WITH CLR V/D BUTTION WHILE PUMP IS RUNNING.

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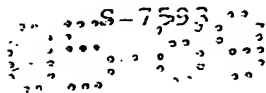


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126 ;      |      |      | THE DISPLAY HAS BEEN CHANGED TO EYE ERR IF
127 ;      |      |      | THE IR SENSOR IS BLOCKED DURING TEST SEQUENCE.
128 -----
129 ;
130 ; 7/25/87 | 010.0 | MODIFY DOSE DEL ERROR, SO THAT PRESSING HOLD
131 ;      |      |      | BUTTON ONCE DISABLED ALARM AND MESSAGE. THIS
132 ;      |      |      | WILL ALLOW THE USER TO UPDATE DOSE OR VOLUME
133 ;      |      |      | WITH THE NEXT KEY STROKE.
134 -----
135 ;
136 ; 7/21/87 | 009.0 | modified to display DP scroll when motor on
137 ;      |      |      | in LOW BAT state.
138 -----
139 ;
140 ; 7/16/87 | 008.0 | MODIFY HOLD BUTTON OPERATION FOR LO BAT STATE.
141 ;      |      |      | WHEN HOLD PRESSED, ALARM STOPS AND MOTOR STOPS.
142 -----
143 ;
144 ; 7/13/87 | 007.0 | ADD NO SET FEATURE.
145 ;      |      |      | MODIFY VOLUME DISPLAY. ADD SHORTED MOTOR SENSOR
146 ;      |      |      | DETECTION SOFTWARE. MODIFY 24 HR TIME ROUTINE
147 ;      |      |      | TO CLEAR VOL DELIVERED, BUT NOT TO KILL POWER.

```

```
148 ;-----
149 ; 7/10/87 | 006.0 | FIX HIGH RATE ERROR BUG. MODIFY LOW BAT TO
150 ; | | CONTINUE TO RUN MOTOR WITH ALARM.
151 ;-----
152 ;
153 ; 7/08/87 | 005.0 | TRY NEW INCREMENT METHOD FOR DOSE.
154 ; | | SAVES APPROX. 40 BYTES. ADDED LOW BAT TIMER,
155 ; | | AND DEAD BAT SIGNAL.
156 ;-----
157 ;
158 ; 7/07/87 | 004.0 | 324 RATE INCREMENT CHANGED TO 5 ML FOR RATES
159 ; | | GREATER THEN 50.
160 ;-----
161 ; | |
162 ; 6/29/87 | 003.0 | DOSE FEATURE IS ADDED. CURRENT SENSE SOFTWARE FOR
163 ; | | SET DETECTION DELETED.
164 ; | |
165 ;-----
166 ; 6/25/87 | 002.0 | RATE INITIALIZED TO 0 ON POWER UP AND
167 ; | | TURN-ON. WRAP AROUND OF DISPLAY REMOVED.
168 ;
169 ;-----
```



170	;	;	;	;
171	;	6/01/87	001.0	FIRST PUMP VERSION SEPARATED
172	;	;	;	FROM COMBO2.ASM
173	;	;	;	
174		SEJECT		

VSDOCID: <EP_____0327209A2_I_>

```

197 ;
198 ;
199 ;
200 ;
201 ; 7 6 5 4 3 2 1 0
202 ; F1500/ AC/DC /DROP /IO BAT /SET /OFF /B /A /A
203 ; PUMP
204 ;
205 ;
206 ;
207 ;
208 ;
209 ;
210 ;
211 ; 7 6 5 4 3 2 1 0
212 ; NC IR-LED NC CLEAR VOLUME /HOLD /DOSE 1/3
213 ; ON/OFF REV
214 ;
215 ;
216 ;
217 ;
218 $EJECT

```

C ALL INPUTS

D 0,1,2,3,4, INPUTS
5,6 OUTPUTS

```

219      DEFSEG ABSLSEG,ABSOLUTE
220      SEG ABSLSEG
221      ;
222      ;
223      ;***** SET UP RAM/ROM AND PORT ADDRESSES *****
224      ;
225      USRRAM EQU $40      ;STARTING ADDRESS OF USER RAM.
226      USRRROM EQU $1000   ;STARTING ADDRESS OF USER ROM.
227      PMPTST EQU $1C00    ;STARTING ADDRESS OF PUMP TEST SOFTWARE.
228      ;
229      PORTA EQU $00        ;PORT A DATA.
230      PORTB EQU $01        ;PORT B DATA.
231      PORTC EQU $02        ;PORT C DATA.
232      PORTD EQU $03        ;PORT D DATA.
233      ;
234      DDRA EQU $04         ;PORT A DATA DIRECTION REGISTER.
235      DDRB EQU $05         ;PORT B " " " "
236      DDRC EQU $06         ;PORT C " " " "
237      DDRD EQU $07         ;PORT D " " " "
238      TDR EQU $08          ;TIMER DATA REGISTER.
239      TCR EQU $09          ;TIMER CONTROL REGISTER.
240      MISC EQU $0A         ;MISCELLANEOUS REGISTER

```

```

241 ;
242 ; *****
243 ; EQUATES
244 ; *****
245 ;
246 TABLE1 EQU $101C
247 TABLE5 EQU $1000
248 ;
249 TIMEST EQU $02
250 ;
251 T8MS EQU $03
252 T33MS EQU $03
253 T1S EQU $0F ;1/2 SEC TIME CONSTANT
254 T6M EQU $02 ;(02 + 1) = 03 x 2.0 = 6 MINUTES
255 T142S EQU $EF ;(EF + 1) = 240 x 0.5 = 2 MINUTES
256 ;
257 ;
258 ;***** INTERRUPT/RESET VECTOR TABLE *****
259 ;
260 =1FF4 ORG $1FF4
261 ;
262 1FF4 102D DW RESET ;SERIAL INTERRUPT TIMER 2

```

1FF6 1089	263	DW	TIMINP	;TIMER INTERRUPT VECTOR (WAIT STATE)
1FF8 1089	264	DW	TIMINP	;TIMER INTERRUPT VECTOR
1FFA 103E	265	DW	ONPOW	;EXTERNAL INTERRUPT VECTOR
1FFC 103E	266	DW	ONPOW	;SOFTWARE INTERRUPT VECTOR
1FFE 102D	267	DW	RESET	;RESET VECTOR
	268		;	
	269		;	
	270		\$EJECT	


```

271 ;
272 ;***** DEFINE VARIABLES IN USER RAM AREA *****
273 ;
274 ;
275 =0040          ORG      USRRAM
276 ;
277 TS            DB      0      ;READING OFF BRIDGE BEFORE RISE BEGINS (AMBIENT)
278 T5            DB      0      ;READING FROM AMP 5 SECOND AFTER BRIDGE RISE.
279 T10           DB      0      ;      "      10
280 T15           DB      0      ;      "      15
281 T20           DB      0      ;      "      20
282 T25           DB      0      ;      "      25
283 ;
284 ALGO          DB      0
285 ;
286 TIMLO         DB      0      ;LOWER BYTE OF 5 MINUTE DOWN COUNTER.
287 TIMHI         DB      0      ;UPPER " " " "
288 ;
289 BATIM1        DB      0      ;15 MIN BATTERY TIMERS
290 BATIM2        DB      0
291 ;
292 HLDTIM1       DB      0      ;HOLD TIME COUNTERS: 2 1/2 MIN

```

```

004C 00      293      HLDIM2 DB      0
                294      ;
004D 00      295      SAMPLE1 DB      0      ;STORAGE FOR THE LAST 5 A-TO-D READINGS.
004E 00      296      SAMPLE2 DB      0      ;(SAMPLE5 IS THE MOST RECENT).
004F 00      297      SAMPLE3 DB      0
0050 00      298      SAMPLE4 DB      0
                299      ;
0051 00      300      DSPDG1 DB      0      ;7-SEGMENT DATA FOR LSD. (BIT 7 IS BACKPLANE CLOCK)
0052 00      301      DSPDG2 DB      0      ;" " " " DIG 2.
0053 00      302      DSPDG3 DB      0      ;" " " " DIG 3. (BIT 7 IS POWER CONTROL)
0054 00      303      DSPDG4 DB      0      ;" " " " MSD. (BITS 7-3 ARE A/D CONTROL)
                304      ;
                305      ;
                306      ;
0055 00      307      DS1 DB      0      ;CONTAINS FIRST TWO DIGITS OF DOSE
0056 00      308      DS2 DB      0      ;CONTAINS LAST TWO DIGITS OF DOSE
                309      ;
                310      ;      DS1 AND DS2 ARE TRANSFERRED TO SAMPLE1-SAMPLE4 BY BCDEXP
                311      ;      ROUTINE.
                312      ;
0057 00      313      DOSECT DB      0      ;COUNTER FOR TIME IN DOSE MODE
                314      ;

```

```

315 ; VS1 AND VS2 ARE TRANSFERRED TO SAMPL1-SAMPL4 BY BCDEXP
316 ;
317 DECML1 DB 0 ;FRACTION OF 1ML IN VOLUME
318 VS1 DB 0 ;CONTAINS FIRST TO DIGITS OF VOLUME
319 VS2 DB 0 ;CONTAINS LAST TO DIGITS OF VOLUME
320 ;
321 REG1 DB 0 ;TEMPORARY STORAGE
322 ;
323 REG2 DB 0 ; "
324 ;
325 DRCNT1 DB 0 ;DROP COUNTERS
326 DRCNT2 DB 0
327
328 REG3 DB 0 ; "
329 REG4 DB 0 ; "
330 REG5 DB 0 ; "
331 ;
332 ;
333 ;
334 ;
0058 00
0059 00
005A 00
005B 00
005C 00
005D 00
005E 00
005F 00
0060 00
0061 00

```

```

0062 00      COUNT1 DB 0      ;GENERAL PURPOSE COUNTER REGISTER.
0063 00      COUNT2 DB 0      ;      "      "      "
0064 00      COUNT3 DB 0      ;      "      "      "
338 ;
339 ;***** REGISTERS AND VARIABLES USED DURING PREDICTION *****
340 ;
341 ;
342 XH DB 0      ;ARGUMENT STORAGE FOR 16-BIT MATH ROUTINES.
343 XL DB 0      ;      "
344 QH DB 0      ;      "
345 QL DB 0      ;      "
346 PH DB 0      ;      "
347 PL DB 0      ;      "
348 ;
349 TEMPA DB 0
350 TEMPX DB 0
351 ;
352 PSTAT1 DB 0      ;FIRST PUMP STATUS BYTE
353 ;      0=HOLD      1=Unit on hold
354 ;      1=MOTOR      1=Motor on
355 ;      2=ON      1=Unit on
356 ;      3=START      1=Unit in start mode

```

```

357 ;
358 ;
359 ;
360 ;
361 ;
362 ;
363 PSTAT2 DB 0 ;SECOND PUMP STATUS BYTE
364 ;
365 LOWBAT EQU PSTAT2 0=BATTERY 1=Low battery
366 ACON EQU PSTAT2 1=AC 1=AC ON
367 NDROP EQU PSTAT2 2=FLOW 1=Drop error
368 HOLDER EQU PSTAT2 3=HOLD 1=Hold error
369 NOSET EQU PSTAT2 4=SET 1=No set error
370 ALRM EQU PSTAT2 5=ALARM 1=Audio alarm on
371 VOIM EQU PSTAT2 6=VOLUME 1=Volume mode
372 ERRON EQU PSTAT2 7=ERROR 1=Error mode
373 ;
374 TSTERR DB 0 ;B0 IS TEST ERROR FLAG
375 ; SET IF EVES BLOCKED DURING TEST
376 ;
377 DOSER DB 0 ;DOSE DELIVTRED FLAG B0=1: DOSE DEL
378 DFLAG DB 0 ;DOSE MODE FLAG

```

4=DISPLAY 1=Display on
5=CW 1=Clock wise rate change
6=CCW 1=Counter clock wise rate change
7=MODEL 1=324 0=224 Model

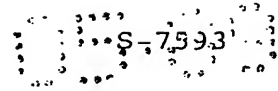
006E 00
006F 00
0070 00
0071 00

```

379 ; B0= DOSE 1=DOSE MODE ON
380 ; B1= DTEST 1=DOSE BUTTON PRESSED
381 ; LAST CYCLE, USED FOR
382 ; DEBOUNCE.
383 ; B2= ZERO 1=DISPLAY ZERO
384 ;
0072 00 LTEST DB 0 ;MAGNET LOW COUNTER, USED TO CHECK IF SENSOR
385 ; IS STUCK LOW. INCREMENTED AS LONG REV SIGNAL
386 ; IS LOW. CLEARED WHEN SIGNAL GOES HIGH.
0073 00 HTEST DB 0 ;B0 - TEST FLAG FOR HOLD DEBOUNCE
387 ;
388 ; B1 - TEST FLAG FOR CIR VOL DEBOUNCE
389 ;
0074 00 ZEROST DB 0 ;ZERO STATUS FLAG
390 ;
391 ; B5 = 1 : DISPLAY IS ZERO
392 ; B6 = 1 : MSD IS ZERO
393 ; B7 = 1 : MSD-1 IS ZERO
394 ;
0075 00 VFLAG DB 0 ;VOLUME DISPLAY TEST FLAG. SET WHEN 'VOL'
395 ; IS DISPLAYED.
0076 00 CWF DB 0 ;CLOCKWISE FLAG
396 ;
0077 00 CCWF DB 0 ;COUNTER CLOCKWISE FLAG
397 ;
0078 00 SPEED1 DB 0 ;ROLL UP/DOWN SPEED
398 ;
0079 00 VOLTIM DB 0 ;VOLUME MODE ON TIMER

```

3NSDOCID: <EP_____0327209A2_1_>



```

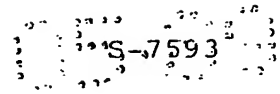
419 ; *****
420 ;          CONSTANTS IN ROM
421 ; *****
422 ;
      LO      DB      $F8,$9C,$FF      ;DISPLAY LO ON LEDS
      BATT    DB      $98,$81,$B8      ;DISPLAY BAT ON LEDS
      FLO     DB      $B1,$F8,$C0      ;DISPLAY FLO ON LEDS
      ERR     DB      $B0,$BD,$BD      ;DISPLAY ERR ON LEDS
      NO      DB      $9D,$9C,$FF      ;DISPLAY NO ON LEDS
      SET     DB      $92,$B0,$B8      ;DISPLAY SET ON LEDS
      HLD     DB      $89,$F8,$8C      ;DISPLAY HLD ON LEDS

      DOSE    DB      $8C,$9C,$92,$B0      ;DISPLAY DOSE ON LEDS
      DEL     DB      $8C,$B0,$F8      ;DISPLAY OUT ON LEDS
      SYS     DB      $92,$8A,$92      ;DISPLAY SYS ON LEDS
      DIGITS  DB      $C0,$CF,$A4,$86,
      $8B     ;DISPLAY NUMBERS 0-9 ON LED
      DB      $92,$90,$C7,$80,
      $83
      ;
      DNUM    DB      $F7,$FB,$FD,$FE      ;DIGIT OUTPUT
423
424
425
426
427
428
429

1015 8C 9C 92 B0
1019 8C B0 F8
101C 92 8A 92
101F C0 CF A4 86
1023 8B
1024 92 90 C7 80
1028 83

1029 F7 FB FD FE

```

437 ;
438 ;*****
439 ;
440 \$EJECT

327593

```

441 ;
442 ;-----
443 ;          START FROM RESET
444 ;-----
445 ;
446 ;          (THIS IS THE POWER-ON RESET ENTRY POINT)
447 ;
448 ;*****
449 ;
450 ;
451 102D AE 40      RESET LDX    #$40      ;FIRST, CLEAR RAM.
452 102F 4F          CLR      CLRA
453 1030 F7      CLEAR STA    ,X
454 1031 5C          INCX
455 1032 A3 FF      CPX      #$FF
456 1034 26 FA      BNE      CLEAR
457
458 ;
459 ;          Set up the ports
460 ;
461 1036 CD 1106      JSR      TIMEON      ;GO START TIMER COUNTER
462 1039 1A 0A      BSET     5,MISC      ;SET INT SENSE FOR EDGE AND LEVEL

```

```

463      ;
464      ;      Wait for timer interrupt
465      ;
466      LOOPW  WAIT
103B 8F
103C 20 FD      BRA  LOOPW
467
468      ;
469      $EJECT
    
```

```

470 ;
471 ;
472 ;
473 ;
474 ;
475 ;
476 ;
477 ;
478 ONPOW BC1R 5,MISC ;RETURN INT SENSE TO EDGE LEVEL
479 BRSET 7,ERRON,NOON ;IF IN ERROR MODE DONT DO
480 BRSET 2,PSTAT1,NOON ;DONT DO IF ON
481 ;
482 LDA #19 ;INITIALIZE PUMP STAT REGISTER
483 STA PSTAT1
484 ;
485 ;
486 ;
487 BSET 7,PSTAT1 ;PRESET ID FLAG FOR 324
488 LDA #FF ;PRELOAD ACCA TO SET PORTB ALL OUTPUT
489 BRCLR 6,PORTB,CONON ;IF PORTB(6)=0, PMP IS 324 SO CONTINUE
490 BC1R 7,PSTAT1 ;ELSE, PMP IS 224 SO CLEAR ID FLAG
491 LDA #BF ; AND SET ACCA TO MAKE PORTB(6) INPUT

```

EXTERNAL INTERRUPT HANDLER

```

103E 1B 0A
1040 0E 6E 45
1043 04 6D 42
1046 A6 19
1048 B7 6D
104A 1E 6D
104C A6 FF
104E 0D 01 04
1051 1F 6D
1053 A6 BF

```

```

492      ;
493      CONON STA      DDRB      ;CONFIGURE PORTB TO BF OR FF
494      LDA      #$FF
495      STA      DDRA      ;CONFIGURE PORTA TO ALL OUTPUTS
496      STA      PORTA      ;MAKE PORTA ALL 1'S
497      LDA      #$1F      ;
498      STA      PORTB      ; PORTB=0001 1111
499      LDA      #$60      ;MAKE PORT D 0-4 INPUTS 5,6 OUTPUTS
500      STA      DDRD
501      CLRA
502      STA      PORTD
503      STA      DDRC
504      ;
505
506      ;      Initialize display pointers
507      ;
508      ;SET UP INITIAL DISPLAY
509      ;POINTERS SO DISPLAY
510      ;READS 0
511      ;WHEN THE DISPLAY IS
512      ;ACTIVATED
513      ;

```

ISDOCID: <EP_____0327209A2 I_>

1088 80	536	NOON	RITI
	537	;	
	538	;	
	539	\$EJECT	

VSDOCID: <EP_____0327209A2_I_>


```

1095 CD 12DA      562      JSR  INRATE1      ;GO UPDATE RATE FOR 224
1098 CD 1185      563      JSR  DROPCK      ;GO CHECK FOR DROP
                    564      ;
109B B6 40        565      LDA  TS          ;TEST IF TIME TO DO NEXT TESTS
109D 3C 40        566      INC  TS
109F A1 03        567      CMP  #T8MS
10A1 27 01        568      BEQ  TIME2
10A3 80           569      RTI
                    570      ;
                    571      ; ***** 8 MS LOOP *****
                    572      ;
10A4 3F 40        573      TIME2 CLR TS
                    574      ;
10A6 CD 11CF      575      JSR  RPMCK      ;GO CHECK MOTOR FOR ONE RPM
10A9 CD 1290      576      JSR  MOTCK      ;GO CHECK MOTOR TIME TO TURN ON
10AC CD 12BD      577      JSR  SETCK      ;GO CHECK FOR SET CURRENT
10AF CD 140E      578      JSR  OFFCK      ;GO SEE IF OFF PUSHED
                    579      ;
10B2 B6 41        580      LDA  T5          ;GET STATUS OF SECOND TIMER
10B4 3C 41        581      INC  T5          ;INCREMENT FOR NEXT TIME
10B6 A1 03        582      CMP  #T33MS      ;DOES IT EQUAL 32 MS
10B8 27 01        583      BEQ  TIME3      ;YES SO GO TEST

```

ISDOCID: <EP_____0327209A2_I_>

```

606      ;
        10DA CD 17DD      JSR  ADCD      ;GO TEST AC OR DC
607      ;
        10DD CD 17E6      JSR  BATCK      ;GO DO BATTERY CHECK
608      ;
        10E0 CD 1836      JSR  DBATCK      ;GO CHECK FOR DEAD BATTERY
609      ;
        10E3 CD 184E      JSR  ALARM      ;GO TEST ALARM
610      ;
        10E6 CD 1860      JSR  BLINK      ;GO BLINK DISPLAY
611      ;
        10E9 CD 1909      JSR  HILDER      ;go test if on hold 142sec then error
612      ;
        613      ;
        10EC B6 43      LDA  T15      ;GET TIMER4 STATUS
614      ;
        10EE 3C 43      INC  T15      ;ADD ONE FOR NEXT TIME
615      ;
        10F0 A1 EF      CMP  #T142S      ;DOES IT EQUAL 142 SEC
616      ;
        10F2 27 01      BEQ  TIMES5      ;YES SO GO TIME 5
617      ;
        10F4 80      RTI      ;RETURN TO PROGRAM
618      ;
        619      ;
        620      ; ***** 142 SEC LOOP *****
621      ;
        622      ;
        10F5 3F 43      TIMES5 CLR  T15      ;CLEAR FOR NEXT TIME
623      ;
        624      ;
        625      ;
        10F7 B6 44      LDA  T20
626      ;
        10F9 3C 44      INC  T20
627      ;
        10FB A1 02      CMP  #T6M

```

↓SDOCID: <EP_____0327209A2_I_>

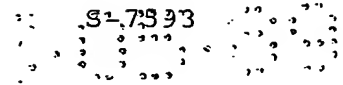
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```

641 ;
642 ; SUBROUTINES
643 ;
644 ;
645 ;
646 ;
647 ; INITIALIZE COUNTER TIMER
648 ;-----
649 ;
650 ;
651 ;
652 ; TIMEON LDA #TIMEST ;SET COUNTER TO 4
653 ; STA TCR ;ENABLE TIMER INT
654 ; CLI ;ENABLE INTERRUPTS
655 ; RTS ;RETURN;
656 ;
657 ;
658 ;
659 ; WATCH DOG TIMER
660 ;-----
661 ; Output clock to hold off reset
662 ;

```

1106 A6 02
1108 B7 09
110A 9A
110B 81



110C 0B 03 03	663	WATCHD	BRCIR 5,PORTD,SEPTR	;IF CLOCK LOW MAKE HIGH
110F 1B 03	664		BCLR 5,PORTD	
1111 81	665		RIS	
	666		;	
1112 1A 03	667		SETR BSET 5,PORTD	
1114 81	668		RIS	
	669		;	
	670		\$EJECT	

```

671 ;
672 ;
673 ;
674 ;
675 ;
676 ;
677 ;
678 ;
679 ;
680 ;
681 ;
682 ;
683 ;
684 ;
685 ;
686 ;
687 ;
688 ;
689 ;
690 ;
691 ;
692 ;

```

LED MUX ROUTINE

This routine is called every 4 ms
It handles 0 suppression and outputs 7 seg data
VARIABLES USED: COUNT3=This is the digit number and is changed every
time this routine is called.
SAMPLE1=location of Current value of digit 1.
add count3 and use as pointer.
7,pstat2 (error)=test if in error mode for blinking.
4,pstat1 (display)=test if display blanked (blinking
mode).
ZEROST=bit 6 set=zero in msd
bit 7 set=zero in next digit

```

1115 05 6D 36 LED BRCLR 2,PSTAT1,NOD4 ;IF UNIT OFF DONT DO MUX
1118 A6 0F LDA #$0F ;Turn all digits off
111A BA 01 ORA PORTB

```

```

111C B7 01      693      STA      PORTB
111E BE 64      694      LDX      COUNT3      ;GET CURRENT DIGIT NO.
1120 A3 03      695      CPX      #$03      ;HAVE WE DONE 4
1122 26 04      696      BNE      GO      ;IF NOT GO ON
1124 3F 64      697      CLR      COUNT3      ;IF SO RESET ALL VARIABLES
1126 20 02      698      BRA      GO2
1128 3C 64      699      ;
1130 00 00      700      GO      INC      COUNT3
1132 00 00      701      ;
1134 00 00      702      GO2      BRSET 6,VOLM,NOTZRO      ;IF IN VOL NO ZERO TEST
1136 00 00      703      BRSET 0,DFLAG,NOTZRO      ;IF IN DOSE NO ZERO TEST
1138 00 00      704      CPX      #$03      ;IF DIGIT 1 DONT TEST FOR 0
113A 00 00      705      BEQ      NOTZRO
113C 00 00      706      JSR      TEST0      ;GO TEST
113E 00 00      707      BCC      NOTZRO      ;IF NO CARRY IT CANT BE 0
1140 00 00      708      BRA      ZERO
1142 00 00      709      ;
1144 00 00      710      ;
1146 00 00      711      NOTZRO      LDA      SAMPLE1,X
1148 00 00      712      BRSET 7,ERRON,OUT1      ;IF error mode dont blank
114A 00 00      713      BRSET 4,PSTAT1,OUT1      ;if display on flag set dont blank
114C 00 00      714      CIRA      ;blank display if display flag is low

```



```

1144 43      715      COMA      ;SET PORTA=FF ALL OFF
              716      ;
1145 B7 00   717      OUT1 STA  PORTA
1147 D6 1029 718      LDA  DNUM,X      ;GET DIGIT TO OUTPUT
114A B4 01   719      AND  PORTB      ;ENABLE
114C B7 01   720      STA  PORTB
114E 81      721      NOD4 RTS
              722      ;
              723      ;
114F A3 00   724      ZERO CPX  #$00      ;IS THIS FIRST TIME THROUGH (MSD)
1151 27 17   725      BEQ  ZERO1      ;IF SO BLANK AND SET FLAG IF ZERO
1153 A3 01   726      CPX  #$01      ;IS THIS SECOND TIME THRU
1155 27 17   727      BEQ  ZERO2      ;IF SO CHECK FIRST FLAG
1157 0D 74 E1 728      BRCLR 6,ZEROST,NOTZRO ;ON THIRD TIME CHECK FIRST TWO
115A 0F 74 DE 729      BRCLR 7,ZEROST,NOTZRO ;IF EITHER NOT SET DONT BLANK
              730      ;
115D E6 4D   731      ZEROT LDA  SAMPL1,X  ;GET DIGIT DATA
115F 49      732      ROLA      ;CHECK IF DP ON
1160 24 04   733      BCC  ZERODP      ;IF SO LEAVE ON
1162 A6 FF   734      LDA  #$FF      ;IF NOT BLANK
1164 20 DF   735      BRA  OUT1      ;GO OUTPUT IT
1166 A6 7F   736      ZERODP LDA  #$7F      ;LEAVE DP ON

```

```

1168 20 DB          BRA OUT1
737
738 ;
739 ;
116A 1C 74          ZERO1 BSET 6,ZEROST ;SET ZERO FLAG
116C 20 EF          BRA ZEROT ;OUTPUT BLANK
740
741
116E 0D 74 CA          ZERO2 BRCIR 6,ZEROST,NOTZRO ;CHECK FIRST DIGIT FLAG
742
743 BSET 7,ZEROST ;IF SET THEN BLANK 2ND DIGIT
1171 1E 74          BRA ZEROT
744
745 ;
1175 E6 4D          TEST0 LDA SAMPL1,X ;test if digit is 0
746
747 CLC
1178 49          ROLA
748
1179 A1 80          CMP #80
749
117B 27 04          BEQ SETCAR
750
117D 98          CLC ;clr carry if not zero
751
117E E6 4D          LDA SAMPL1,X
752
1180 81          RJS
753
1181 99          SETCAR SEC ;set carry if it is
754
1182 E6 4D          LDA SAMPL1,X
755
1184 81          RJS
756
757 ;
758 $EJECT

```

```

759 ;
760 ; DROP CHECK
761 ;
762 ; This routine is called every 8ms
763 ; After a delay of .4 sec to clear all transients,
764 ; it turns on the IR source and looks at the photo transistor.
765 ; If the line is low a drop is there the counter is cleared.
766 ; If there is no drop the counter is incremented and if it reaches
767 ; a count of 95 or 95 X .008=.76 sec then the second counter is incremented
768 ; This counter is tested in the RPM routine if it gets to 2 or 1.76s then
769 ; it will alarm.
770 ;
771 ; -----
772 ; Conditions
773 ;
774 1185 05 6D 43 DROPCK BRCLR 2,PSTAT1,NODRP ;DONT DO IF UNIT OFF
775 1188 00 6D 40 BRSET 0,PSTAT1,NODRP ;DONT DO IF PUMP NOT IN RUN MODE
776 ;
777 ; CHECK RATE
778 ;
779 118B B6 53 LDA DSPDG3 ;IF RATE < 100, CHECK FOR DROPS
780 118D A1 01 CMP #501

```

```

118F 25 03      781      BLO DELCK
1191 03 6D 37   782      BRCLR 1,PSTAT1,NODRP  ELSE, CHECK DROPS WHEN MOTOR ON ONLY
783      ;
784      ;      DELAY CHECK
785      ;
786      DELCK LDA REG1      ;CHECK REG1
1194 B6 5B      787      CMP #124      ;IF 0.248 SEC ELAPSED SINCE MOTOR ON
1196 A1 7C      788      BEQ DROP1      ;DO DROP TEST AND SKIP INCREMENT.
1198 27 04      789      INCA      ;ELSE,
119A 4C      790      STA REG1      ;INCREMENT AND RETURN.
119B B7 5B      791      RTS
119D 81      792      ;
793      ;      Test for drop
794      ;
119E 1C 03      795      DROP1 BSET 6,PORTD      ;TURN IR SOURCE ON
11A0 9D      796      NOP      ;ADD SOME DELAY TO ALLOW SETTLING
11A1 9D      797      NOP
11A2 9D      798      NOP
11A3 9D      799      NOP
800      ;
11A4 0A 02 1C   801      BRSET 5,PORTC,CLERK      ;CHECK FOR LOW (DROP)
11A7 1D 03      802      BCLR 6,PORTD      ;TURN OFF IR SENSOR

```

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```

11A9 10 81      803      BSET 0,COUNT4      ;WE HAVE DROP SO SET FLAG
                        804      ;
11AB 3C 5D      805      INC  DRCNT1          ;INCREMENT DROP COUNTERS
11AD 26 02      806      BNE  CONDRP
11AF 3C 5E      807      INC  DRCNT2
11B1 B6 5E      808      CONDRP  LDA  DRCNT2      ;CHECK IF DROP CNT = 0.76 SEC
11B3 A1 01      809      CMP  #$01
11B5 25 14      810      BLO  NODRP          ;IF DRCNT2 < 1 END TEST
11B7 B6 5D      811      LDA  DRCNT1          ;ELSE CHECK DROP CNT 1
11B9 A1 7C      812      CMP  #$7C
11BB 27 02      813      BEQ  NEXTBY          ;IF DRCNT1 >= 7C, INCREMENT REG3
11BD 20 0C      814      BRA  NODRP          ;ELSE, EXIT DROPCK
                        815      ;
11BF 3C 5F      816      NEXTBY  INC  REG3
11C1 20 08      817      BRA  NODRP          ;REG3 IS TESTED IN THE RPM ROUTINE
                        818      ;
                        819      ;
                        820      ;          No drop
                        821      ;
11C3 1D 03      822      CLERK BCLR 6,FORTD
11C5 3F 5D      823      CLR  DRCNT1          ;CLEAR THE COUNTERS FOR BLOCKED EYES
11C7 3F 5E      824      CLR  DRCNT2

```

11C9 3F 5F	825	CLR	REG3
11CB 81	826	NODRP RIS	
	827	;	
	828	;	
	829	\$EJECT	

```

830 ;
831 ;
832 ;
833 ; RPM CHECK
834 ;-----
835 ; This routine samples the hall effect line. At rates over 95 it stops
836 ; the motor every 3 magnets or one rev. At rates under 100 it stops
837 ; every magnet 1/3 rev.
838 RPM3 JMP RPM1
839 ;
840 ; Conditions
841 ;
842 RPMCK BRCIR 2,PSTAT1,NODRP ;DONT DO IF UNIT OFF
843 BRCIR 1,PSTAT1,NODRP ;DON'T DO IF MOTOR IS OFF
844 ;
845 ; Delay until circuit settles
846 ;
847 LDA MOTIM2 ;DON'T DO IF MOTOR NOT RUN ENOUGH
848 BNE RPM2 ;IF 2ND BYTE >0 THEN DO TEST
849 LDA MOTIM1 ;IF=0M THEN TEST 1ST BYTE FOR>$32
850 CMP #86 ;
851 BLO NODRP ;IF <THEN 86*.00816=.7017 SEC THEN DONT DO

```

```

852 ;
853 ; Test magnet
854 ;
855 RPM2 BRSET 0,PORTD,RPM3 . ;IF LINE HIGH THERE IS NO MAGNET
856 CLR ERRCNT
857 INC LTEST ;UPDATE MAG LOW COUNTER
858 LDA LTEST
859 CMP #255 ;IF MAG SENSED FOR 2 CONS. SEC
860 BEQ TIMERR ;THEN MAGNET OR ROTOR ERROR.
861 CMP #501 ;IF LTEST > 1,
862 BHI NORPM ;SAME PULSE DETECTED SO DON'T UPDATE
863 ;
864 ;----- If this is model 324 add .376 to volume for every rev -----
865 ;
866 BRCIR 7,PSSTAT1,OFMOT1 ;IF 224 DONT ADD
867 ;
868 JSR CALCV ;ELSE, CALCULATE VOLUME
869
870 ;
871 ;
872 XYZV BRCIR 6,VOIM,OFMOT ;IF NOT IN VOLUME MODE OR
873 BRSET 0,VFLAG,OFMOT ;VOL TEST DISPLAY ENABLED

```



```

11FC CD 1634      874      JSR    VSEXP      ;GO UPDATE VOLUME NUMBERS
                   875      ;
                   876      ;
                   877      ;
                   878      ;
                   879      ;      Test 1/3 OR 1 REV AND Turn off the motor
                   880      ;
                   881      OFMOT LDA DS1      ;IF DOSE!=0, CHECK DOSE
                   882      ORA DS2
11FF B6 55
1201 BA 56

1203 26 36      883      BNE    CMPDOS
                   884      ;
1205 3F 5B      885      OFMOT1 CLR REG1
1207 3C 61      886      INC REG5      ;CHECK IF THIS IS START UP
1209 B6 61      887      LDA REG5      ;IF SO IGNORE THE FIRST MAGNET
120B A1 02      888      CMP #02      ;AS IT COULD BE LESS THEN 1/3
120D 25 20      889      BLO NORPM      ;IT IS SO JUMP OVER SET CHECK
                   890      ;
120F 3A 61      891      DEC REG5      ;ITS NOT START SO KEEP FROM OVERFLOW
1211 3C 7A      892      INC THIRD1
1213 B6 7A      893      LDA THIRD1

```

```

1215 A1 03      894      CMP    #03
1217 26 0A      895      BNE    OFF90
1219 3F 7A      896      CLR    THIRD1
                        897      ;
                        898      ;      If drop flag not set then error
                        899      ;
121B 01 81 43   900      BRCLR 0,COUNT4,DROPER
121E 02 5F 40   901      BRSET 1,REG3,DROPER      ;EYES BLOCKED FOR 1 REV
                        902      ;
1221 3F 81      903      CLR    COUNT4
1223 B6 53      904      OFF90 LDA  DSPDG3      ;CHECK IF >95 RATE
1225 26 31      905      BNE    STP3      ;IF RATE >100 THEN STOP EVERY 3 SENSORS
1227 20 02      906      BRA    OFFM1
                        907      ;
1229 10 6D      908      OFFM BSET 0,PSTAT1      ;SET HOLD FLAG TO DISABLE MOTCK
122B 13 6D      909      OFFM1 BCLR 1,PSTAT1      ;MOTOR OFF PSTAT
122D 1B 01      910      BCLR 5,PORTB      ;MOTOR OFF
122F 81         911      NOREM RTS
                        912      ;
                        913      ;
                        914      ;
                        915      ;

```

```

916 ;
917 ;      Reset pulse status
918 ;
919 REM1 CIR      LTEST      ;CLEAR MAG LOW COUNTER
920 INC ERRCNT
921 LDA ERRCNT
922 CMP #255      ;IF NO MAGNET IN 255X.008=2.04 SEC THEN ERR
923 BEQ TIMERR
924 RTS
925 ;
926 ;
927 CMPDOS JSR    CPVTOD      ;CALL COMPARE VOL TO DOSE
928 CPX  #FFF      ;X IS FF IF VOL >= DOSE
929 BNE OFMOIT1     ;IF X NOT FF, CONTINUE
930 ;              ;ELSE DOSERR
931 ;
932 DOSERR BSET 0,DOSER
933 LDA PSTAT2
934 ORA  #A0
935 AND  #BD

```

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```

124A B7 6E      STA  PSTAT2
124C 20 DB      BRA  OFFM
936             ;
937             ;
938             ;
939             ;
940             TIMERR      BSET 7,ERRON      ;ENABLE ERROR FLAG
941             BSET 5,AIRM      ;ENABLE ALARM
1250 1A 6E      CLR  ERRCNT
942             JSR  OFFM
1252 3F 7F
1254 CD 1229
1257 81      RTS
943
944
945             ;
946             ;      Count every 3 magnet hits
947             ;
948             STP3  INC  THIRDR      ;BUMP THIRD OF A REV COUNTER;
1258 3C 7B      LDA  THIRDR
949             CMP  #$03      ;IF THIRD ONE THEN STOP
125A B6 7B
125C A1 03      BHS  OFFM1      ;DONT SET HOLD FLAG
125E 24 CB      RTS
1260 81
950
951
952             ;
953             ;
954             ;      No drop error
955             ;
956             ;
957             DROPER      BSET 2,NDROP      ;SET FLOW ERROR FLAG

```

```

1263 1E 6E      BSET 7,ERRON      ;ENABLE DISPLAY ERROR MODE
1265 1A 6E      BSET 5,AIRM       ;ENABLE ALARM ERROR
1267 1D 6E      BCIR 6,VOLM      ;GET OUT OF VOLUME MODE
1269 11 71      BCIR 0,DFLAG     ;CLEAR DOSE MODE FLAG
126B 20 BC      BRA  OFFM
;
958             ;
964             ;      .125 ml/ 1/3 rev 8*.125=1
965             ;
126D 3C 58      CALCV INC DECML1  ;INCREMENT DECML COUNTER
126F B6 58      LDA  DECML1
1271 A1 08      CMP  #$08        ;IF DECML=8, TIME TO INCREMENT VS1, VS2
1273 26 1A      BNE  ENDCALC     ;ELSE, ENDCALC
;
1275 3F 58      CLR  DECML1      ;CLEAR DECML COUNTER
;
1277 A6 99      LDA  #$99        ;CHECK FOR FULL COUNTER
1279 B1 59      CMP  VS1
127B 26 04      BNE  CONCAL      ;IF VS1 != 99, CONTINUE CALCULATION
127D B1 5A      CMP  VS2        ;ELSE, CHECK VS2
127F 27 0E      BEQ  ENDCALC     ;IF VS1 & VS2 = 99, END CALCULATION
;
1281 B6 59      CONCAL LDA VS1   ;INCREMENT VS1

```

1283 AB 01	980	ADD #S01	
1285 8D	981	DAA	;DECIMAL ADJUST RESULT
1286 B7 59	982	STA VS1	;STORE VS1
	983	;	
1288 B6 5A	984	LDA VS2	;ADD VS2
128A A9 00	985	ADC #S00	
128C 8D	986	DAA	;DECIMAL ADJUST RESULT
128D B7 5A	987	STA VS2	;STORE RESULT
128F 81	988	ENDCALC RTS	
	989	;	
	990	\$EJECT	

```

991 ;
992 ;          TIMING THE MOTOR
993 ;-----
994 ; This routine compares the calculated vs. timed motor on time and restarts
995 ; the motor every time they are equal.
996 ; The motor is turned off in the rpm routine>
997 ; the calculated values are generated by the UPDATE subroutine.
998 ;
999 ; Variables: MOTIM1=INCREMENTED EACH TIME
1000 ;           MOTIM2=INCREMENTED EACH TIME MOTIM1 OVERFLOWS
1001 ;           TIMLO= CALCULATED FIRST BYTE OF TIME ON GENERATED IN UPDATE
1002 ;           TIMHI= CALCULATED SECOND BYTE OF TIME
1003 ;
1004 ;           Conditions
1005 ;
1006 ;           MOTCK BRCLR 2, PSTAT1,END1 ;DONT DO IF UNIT OFF
1007 ;           BRSET 0, PSTAT1,END1 ;DON'T DO IF HOLD
1008 ;           BRSET 7, ERRON,END1 ;DON'T DO IF ERROR MODE
1009 ;           BRSET 3, PSTAT1,END1 ;DONT DO IF START MODE
1010 ;
1011 ;           ABOVE LINES DELETED TO ALLOW MOTOR TO
1012 ;           PUMP WITH LO BAT ERROR

```

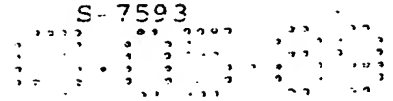
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```

1045 ;
1046 ;
1047 ; SET CHECK
1048 ;-----
1049 ; Conditions
1050 ;
1051 SETCK BRCIR 2,PSTAT1,NOSCK ;DONT DO IF UNIT OFF
1052 BRSET 3,PSTAT1,NOSCK ;DONT DO IF UNIT IS IN START MODE
1053 BRSET 0,PSTAT1,NOSCK ;DONT DO IF UNIT IS IN HOLD
1054 ;
1055 ; CHECK FOR PROPER SET PLACEMENT
1056 ;
1057 BRCIR 3,PORTC,NOSCK ;IF SET PRESENT, RETURN
1058 ; ELSE SET ERROR
1059 BSET 4,NOSET ;ENABLE SET ERROR FLAG
1060 BSET 7,ERRON ;ENABLE ERROR MODE
1061 BSET 5,ALRM ;ENABLE AUDIO ALARM
1062 BCIR 6,VOLM ;GET OUT OF VOLUME MODE
1063 BCIR 0,DFLAG ;CLEAR DOSE MODE FLAG
1064 BCIR 1,PSTAT1 ;CLEAR MOTOR ON FLAG
1065 BCIR 5,PORTB ;TURN OFF MOTOR
1066 BSET 0,PSTAT1 ;SET HOLD FLAG TO DISABLE MOTCK

```



1067.	;	NOSCK RPS	
1068			12D9 81
1069			
1070			
1071			
1072			
1073		\$EJECT	

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12FB B7 82	1096	STA	ISTRAT		;STORE RATE POSITION FOR NEXT TIME
	1097				
12FD A1 01	1098	CMP	#\$01		;BEGIN DECODING DEC POSITIONS
12FF 27 64	1099	BEQ	DECRI		
1301 A1 07	1100	CMP	#\$07		
1303 27 60	1101	BEQ	DECRI		
1305 A1 08	1102	CMP	#\$08		
1307 27 5C	1103	BEQ	DECRI		
1309 A1 0E	1104	CMP	#\$0E		
130B 27 58	1105	BEQ	DECRI		
	1106				
130D A1 02	1107	CMP	#\$02		;BEGIN DECODING INC POSITIONS
130F 27 0D	1108	BEQ	INCRI		
1311 A1 04	1109	CMP	#\$04		
1313 27 09	1110	BEQ	INCRI		
1315 A1 0B	1111	CMP	#\$0B		
1317 27 05	1112	BEQ	INCRI		
1319 A1 0D	1113	CMP	#\$0D		
131B 27 01	1114	BEQ	INCRI		
131D 81	1115	OVER	RIS		
	1116				
	1117				test for increase by one

```

1118 ;
131E 1B 74 INCR1 BCLR 5,ZEROST ;CLEAR DISPLAY ZERO FLAG
1119
1320 16 6D BSET 3,PSTAT1 ;MAKE START ON
1120
1322 18 6D BSET 4,PSTAT1 ;MAKE DISPLAY ON
1121
1324 A6 03 LDA #S03 ;IF 300, RETURN
1122
1326 B1 53 CMP DSPDG3
1123
1328 27 F3 BEQ OVER
1124
1125 ;
132A 0F 6D 1A BRCIR 7,PSTAT1,UPFIVE ;IF MODEL 224 GO UP BY 5 ONLY
1126
1127 ;
1128 ;
132D B6 53 LDA DSPDG3 ;
1129
132F 26 16 BNE UPFIVE ;IF DIGIT 3 IS NOT 0, INCREMENT BY 5
1130
1331 B6 52 LDA DSPDG2
1131
1333 A1 05 CMP #S05
1132
1335 24 10 BHS UPFIVE ;IF DIGIT 2 IS >= 5, INCREMENT BY 5
1133
1134 ;
1337 98 UPONE CLC ;ELSE INCREMENT BY 1
1135
1338 A6 F7 LDA #F7 ;TEST FOR 9
1136
133A BB 51 ADD DSPDG1
1137
133C 25 05 BCS DEC91 ;IF 9 MAKE 0 AND INC NEXT DIGIT
1138
133E 3C 51 INC DSPDG1 ;IF NOT THEN INC BY ONE
1139

```

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```

1162 ;
1163 ;      Increment digit 3 by one
1164 ;
1165 INC3 INC      DSPDG3
1166      BCLR 7,ZEROST
1167 DEC3 JMP      UPDATE
1168 ;
1169 ;      Do a rate decrease
1170 ;
1171 ;      test for decrement by 5
1172 ;
1173 DEC31 BSET 3,PSTAT1 ;MAKE START ON
1174      BSET 4,PSTAT1 ;MAKE DISPLAY ON
1175      BRSET 5,ZEROST,OVER ;IF DISPLAY IS 0 THEN DONT DECR
1176      LDA  DSPDG3      ;PREPARE ACCA FOR ZERO TEST OF
1177      ORA  DSPDG2      ;DSPDG2 AND DSPDG3
1178      BRSET 7,PSTAT1,CH324 ;IF 324 GOTO CH324, ELSE
1179      CH224 BNE  DECR5    ;IF 224 AND DIGIT 2 & 3 ARE NOT ZERO, DECR5
1180      RTS                ;ELSE DONT DECR
1181 ;
1182      CH324 BNE  DECCN    ;IF DIGIT2 & 3 ARE NOT ZERO, CONTINUE
1183      LDA  DSPDG1      ;ELSE, TEST DIGIT 1 FOR 1

```


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```

137A A1 01      1184      CMP      #01
137C 26 13      1185      BNE      DOWN1      ;IF NOT 1,DECR BY 1
137E 81          1186      RTS
                  1187      ;
137F B6 53      1188      DECCN LDA  DSPDG3      ;IF DIGIT3 NOT ZERO,
1381 26 54      1189      BNE      DECR5      ;DECR BY 5
1383 B6 52      1190      LDA      DSPDG2      ;IF DIGIT2 > 5,
1385 A1 05      1191      CMP      #05      ;
1387 22 4E      1192      BHI      DECR5      ;DECR BY 5
1389 25 06      1193      BLO      DOWN1      ;ELSEIF DIGIT2 < 5 DECR BY 1
138B B6 51      1194      LDA      DSPDG1      ;ELSE TEST DIGIT1
138D A1 00      1195      CMP      #00      ;IF DIGIT1 NOT ZERO,
138F 26 46      1196      BNE      DECR5      ;DECR BY 5
                  1197      ;
                  1198      ;
                  1199      ;      DECREMENT BY 1
                  1200      ;
1391 B6 51      1201      DOWN1      LDA      DSPDG1      ;GET DIGIT 1
1393 27 09      1202      BEQ      TET2      ;IF ZERO THEN MAKE 9
1395 A1 01      1203      CMP      #01
1397 27 34      1204      BEQ      CHK300
1399 3A 51      1205      DEC2      DEC      DSPDG1      ;IF NOT THEN JUST DECREMENT

```

```
139B CC 1756      1206      JMP      UPDATE      ;GO UPDATE THE RATE
1207      ;
139E B6 52      1208      TET2 LDA DSPDG2
13A0 26 0B      1209      BNE INC9A
13A2 3A 53      1210      DEC DSPDG3
13A4 A6 09      1211      LDA #$09
13A6 B7 51      1212      STA DSPDG1
13A8 B7 52      1213      STA DSPDG2
13AA CC 1756      1214      JMP      UPDATE
1215      ;
13AD 3A 52      1216      INC9A DEC DSPDG2      ;IF NOT DECREMENT BY ONE
13AF A6 09      1217      LDA #$09      ;MAKE FIRST DIGIT 9
13B1 B7 51      1218      STA DSPDG1
13B3 CC 1756      1219      JMP      UPDATE      ;GO UPDATE THE DISPLAY
1220      ;
13B6 A6 03      1221      GO300 LDA #$03      ;CHANGE DIGIT 3 TO 3
13B8 B7 53      1222      STA DSPDG3
13BA A6 00      1223      LDA #$00      ;MAKE DISPLAY 300
13BC B7 52      1224      STA DSPDG2
13BE B7 51      1225      STA DSPDG1
1226      ;      CLR ZEROST
1227      LDA SPEED1
13C0 B6 78
```

13C2 A1 40	1228	CMP	#\$40		
13C4 25 04	1229	BLO	SPDY1		
13C6 A6 41	1230	LDA	#\$41		
13C8 B7 78	1231	STA	SPEED1		
13CA CC 1756	1232	SPDY1 JMP	UPDATE		
	1233	;			
13CD B6 52	1234	CHK300	LDA	DSPDG2	;IF DIGIT 2 IS ZERO MAKE 300
13CF 26 C8	1235	BNE	DEC2		
13D1 B6 53	1236	LDA	DSPDG3		
13D3 26 C4	1237	BNE	DEC2		
13D5 20 DF	1238	BRA	GO300		
	1239	;			
	1240	;		change rate by 5	
	1241	;			
13D7 4F	1242	DECR5	CLRA		
13D8 B1 53	1243	CMP	DSPDG3		;IF DIGIT 2,3 ARE 0 THEN MAKE 000
13DA 26 0D	1244	BNE	TOG2		
13DC B1 52	1245	CMP	DSPDG2		
13DE 26 09	1246	BNE	TOG2		
13E0 B7 51	1247	STA	DSPDG1		
13E2 A6 03	1248	LDA	#\$03		
13E4 B7 53	1249	STA	DSPDG3		

13E6 CC 1756	1250	;	CLR	ZEROST	
13E9 CD 174B	1251		JMP	UPDATE	
13EC A6 00	1252		TOG2 JSR	TOGGLE	;GO MAKE 0 OR 5
13EE B1 51	1253		LDA	#\$00	
13F0 27 19	1254		CMP	DSPDG1	
	1255		BEQ	INCD3	
	1256	;			
	1257	;		Decrement digit 2 by one	
	1258	;			
13F2 B6 52	1259		LDA	DSPDG2	;GET POINTER
13F4 27 05	1260		BEQ	INC9	;IF 0 THEN MAKE 9
13F6 3A 52	1261		DEC	DSPDG2	;IF>0 THEN SUB 1
13F8 CC 1756	1262		SETZ	JMP	UPDATE
13FB B6 53	1263		INC9	LDA	DSPDG3
13FD 27 0C	1264		BEQ	INCD3	
13FF A6 09	1265		LDA	#\$09	;RESET TO 9
1401 B7 52	1266		STA	DSPDG2	
	1267	;			
	1268	;		Decrement digit 3 by one	
	1269	;			
1403 B6 53	1270		DECD3	LDA	DSPDG3
1405 27 04	1271		BEQ	INCD3	;IF 0 THEN MAKE 2

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1407 3A 53	1272	DEC	DSPDG3						
1409 1F 74	1273		BCLR 7,ZEROST						
140B CC 1756	1274		INCD3 JMP	UPDATE					
	1275		:						
	1276		:						
	1277		\$EJECT						

;>0 SO SUB 1

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1278	;	
1279	;	
1280	;	OFF CHECK
1281	;	
1282	;	Conditions
1283	;	
1284	OFFCK	BRCLR 2, PSTAT1, TSTCK ; IF OFF, CHECK IF TIME FOR TEST MODE
1285	BRCLR	2, PORTC, GOFF ; IF OFF BUTTON PRESSED GO OFF
1414 81	NOOFF	RTS
1287	;	
1288	;	Do off
1289	;	
1290	GOFF	BRSET 0, LOWBAT, KILOP1 ; IF LOW BATT KILL POWER
1418 3F 6E	CLR	PSTAT2 ; NO ALARMS OR OPTIONAL MODES
141A 3F 71	CLR	DLFAG ; CLEAR DOSE FLAG
141C 3F 80	CLR	DSP1ST ; CLEAR DISPLAY TEST FLAG
1294	;	
141E A6 19	LDA	#\$19 ; SET PSTAT1 FOR NEXT TURN-ON
1420 B7 6D	STA	PSTAT1
1422 A6 1F	LDA	#\$1F ; KILL DISPLAY AND MOTOR 0001 1111 OR
1424 B7 01	STA	PORTB
1426 CD 1948	JSR	TIMRST ; CLEAR ALL TIMERS FOR 24HR KEEPING

```

1429 3F 45      1300      CLR      T25
142B 3F 55      1301      CLR      DS1      ;CLEAR DS1 AND DS2 FOR USE AS
142D 3F 56      1302      CLR      DS2      ;3 SEC TEST TIMER.
142F 8F          1303      LOOFP      WAIT      ; GO SLEEP
1430 20 FD      1304      BRA      LOOFP
1305      ;
1306      ;      wake up by on button (external int)
1307      ;
1432 CD 1106     1308      JSR      TIMEON      ;RESET COUNTER TIMER
1435 81          1309      RTS
1310      ;
1436 9B          1311      KILLP1      SEI      ;SET INT MASK TO PREVENT TURN-ON
1437 A6 0F      1312      LDA      #$0F      ;DISABLE PUMP
1439 B7 0B      1313      STA      PORTB
143B 20 F9      1314      BRA      KILLP1      ;LOOP UNTILL POWER DISSIPATES
1315      ;
1316      ;      TEST CHECK
1317      ;
143D 04 02 03     1318      TSTCK BRSET 2,PORTC,TSTOUT      ;IF OFF BUTTON NOT PUSHED, RETURN
1440 05 03 05     1319      BRCLR 2,PORTD,TSTCNT      ;ELSE, IF HOLD BUTTON PRESSED INCREMENT
1320      ;      ; YES COUNTER
1443 3F 55      1321      TSTOUT      CLR DS1

```

1445 3F 56	1322	CLR DS2	
1447 81	1323	RTS	
	1324	;	
1448 3C 55	1325	TSTCNT INC DS1	: INCREMENT TEST TIMER
144A 26 02	1326	BNE TST1	
144C 3C 56	1327	INC DS2	
144E B6 56	1328	TST1 LDA DS2	: IF 3 SEC ELAPSED, GOTO PMPTST
1450 A1 02	1329	CMP #502	
1452 24 01	1330	BHS PTST	
1454 81	1331	RTS	: ELSE RETURN
1455 CC 1C00	1332	PTST JMP PMPTST	
	1333	;	
	1334	\$EJECT	

1458 05 6D 30	1340	TESTD BRCR 2, PSTAT1, NOTST	: DONT DO IF UNIT OFF
145B 01 80 2D	1341	BRCR 0, DSPST, NOTST	: DONT DO IF TEST FLAG NOT SET
145E 0F 6D 2D	1342	BRCR 7, PSTAT1, TSTD2	: IF 224, DO SHORT TEST MODE
1461 3C 79	1343	INC VOLFTM	: DO FOR .033*60=1.98 SEC
1463 B6 79	1344	LDA VOLFTM	
1465 A1 78	1345	CMP #120	: GO CLEAR TEST MODE
1467 22 4F	1346	BHI CLTEST	
1469 A1 64	1347	CMP #100	: GO DISPLAY DOSE NUMBER
146B 22 7B	1348	BHI DOSDIS	
146D A1 50	1349	CMP #80	: GO DISPLAY DOSE
146F 22 66	1350	BHI DOSTST	
1471 A1 3C	1351	CMP #60	: GO DISPLAY VOLUME NUMBER
1473 22 5E	1352	BHI VOLDS	
1475 A1 28	1353	CMP #40	: GO DISPLAY VOL
1477 22 49	1354	BHI VOLNST	
1479 A1 14	1355	CMP #20	: GO KILL ALARM FIRST
147B 22 22	1356	BHI CLATST	

TEST MODE

```

147D 1E 01      1357      CONTST      BSET 7,PORTB      ;ALARM ON
147F 1C 01      1358      BSET 6,PORTB      ;CLEAR LED ON
1481 1C 6E      1359      BSET 6,VOIM      ;SET VOIM FLAG TO ENABL 4 DIGITS
1483 3F 4D      1360      CIR  SAMPL1      ;MAKE DISPLAY "8888"
1485 3F 4E      1361      CIR  SAMPL2
1487 3F 4F      1362      CIR  SAMPL3
1489 3F 50      1363      CIR  SAMPL4
148B 1D 03      1364      NOTST BCIR 6,PORTD      ;TURN IR SOURCE OFF
148D 81         1365      RTS
1366           1366      ;
1367           1367      ; SHORT TEST FOR K224
1368           1368      ;
148E 1C 6E      1369      TSTD2 BSET 6,PSTAT2      ;VOLUME FLAG SET TO ENABLE 4 DIGITS
1490 3C 79      1370      INC  VOLTIM      ;DO FOR .033*60=1.98 SEC
1492 B6 79      1371      LDA  VOLTIM
1494 A1 3C      1372      CMP  #$3C
1496 22 20      1373      BHI  CLTEST
1498 A1 14      1374      CMP  #$14
149A 22 03      1375      BHI  CLATST
149C CC 147D    1376      JMP  CONTST
1377           1377      ;
1378           1378

```

```

149F 1F 01      1379      CLATST      BCLR 7,PORTB      ;TURN ALARM OFF
14A1 1D 01      1380      BCLR 6,PORTB      ;LED OFF
1381      ;
1382      ;      test sensor eyes
1383      ;
1384      BSET 6,PORTD      ;TURN IR SOURCE ON
1385      NOP      ;ADD 8 USEC DELAY TO ALLOW IR
1386      NOP      ;SENSOR TO SETTLE
1387      NOP
1388      NOP
1389      BRSET 5,PORTC,NOTST      ;IF RECIEVER LOW EYES BLOCKED THEN ERROR
1390      BCLR 6,PORTD      ;TURN OFF IR SOURCE
1391      BSET 5,PSTAT2      ;ENABLE ALARM
1392      BSET 2,NDROP      ;ENABLE FLOW ERROR FLAG
1393      BSET 7,PSTAT2      ;ENABLE ERROR FLAG
1394      BCLR 7,PORTB      ;TURN ALARM OFF
1395      BCLR 3,PSTAT1      ;CLEAR START FLAG
1396      ;
1397      CLTEST      JSR UPDATE      ;RESTORE DISPLAY
1398      CLR DSPTST      ;CLEAR TEST FLAG
1399      BCLR 6,VOLM      ;CLEAR VOLUME FLAG FOR 224
1400      CLR VOLTIM      ;CLEAR TIMER

```

527553

```
14C1 81      1401      RTS
                ;
14C2 A6 F8    1402      VOLIST      LDA  #$F8      ;
14C4 B7 50    1403      STA  SAMPLE4
14C6 A6 9C    1404      LDA  #$9C
14C8 B7 4F    1405      STA  SAMPLE3
14CA A6 C8    1406      LDA  #$C8
14CC B7 4E    1407      STA  SAMPLE2
14CE A6 FF    1408      LDA  #$FF
14D0 B7 4D    1409      STA  SAMPLE1
14D2 81      1410      RTS
                ;
14D3 CD 1634  1411      VOLDS JSR  VSEXP
14D6 81      1412      RTS
                ;
14D7 A6 B0    1413      DOSIST      LDA  #$B0
14D9 B7 50    1414      STA  SAMPLE4
14DB A6 92    1415      LDA  #$92
14DD B7 4F    1416      STA  SAMPLE3
14DF A6 9C    1417      LDA  #$9C
14E1 B7 4E    1418      STA  SAMPLE2
14E3 A6 8C    1419      LDA  #$8C
1420          1420
1421          1421
1422          1422
```

14E5 B7 4D	1423	STA	SAMPL1			
14E7 81	1424	RTS				
	1425					
14E8 CD 1745	1426	DOSDIS	JSR	DSEXP		;DISPLAY PROGRAMMED DOSE
14EB 81	1427					
	1428					
	1429					
	1430					
	1431					\$EJECT

```

1432 ;
1433 ; HOLD CHECK
1434 ;-----
1435 ; Conditions
1436 ;
1437 HOLDCK BRCIR 2,PSTAT1,NOHOLD ;IF OFF DONT DO
1438 BRSET 0,DSPTST,NOHOLD ;DONT DO IF TEST MODE
1439 BRSET 0,CWF,NOHOLD ;DONT DO IF INC OR DEC
1440 BRSET 0,CCWF,NOHOLD ;BUTTON IS PRESSED
1441 ;
1442 BRSET 2,PORID,NOH1 ;IS HOLD BUTTON DOWN RETURN IF NOT
1443 ;
1444 ; Hold button down
1445 ;
1446 ; Debounce switch
1447 ;
1448 BRSET 0,HTEST,NOHOLD ;WE MUST BE SEEING SAME PULSE SO IGNORE
1449 BSET 0,HTEST ;IF NOT SAME SET THE FLAG
1450 ;
1451 ; CLEAR HOLD TIME COUNTERS
1452 ;
1453 CLR HLDIMI
1500 3F 4B

```

1502 3F 4C	1454	CIR	HIDTM2	
	1455			
	1456		Check for alarm conditions	
	1457			
1504 00 6E 2F	1458	BRSET 0, LOWBAT, HLD BAT		; IF LOW BAT, STOP ALARM AND MOTOR.
1507 00 70 37	1459	BRSET 0, DOSER, STDSE		; IF DOSE DEL FLAG SET, STOP DOSE MESS.
150A 0A 6E 2F	1460	BRSET 5, ALPM, NOAUDO		; IF WE ARE ALARMING THEN KILL AUDIO
150D 0E 6E 3F	1461	BRSET 7, ERRON, NOMESS		; IF WE ARE FLASHING ERROR MESSAGE THEN GO RUN
1510 0C 6E 34	1462	BRSET 6, VOIM, NOVOIM		; IF IN VOL GO RESTORE RATE
1513 00 71 35	1463	BRSET 0, DFLAG, NODOS		; IF DOSE MODE, GO RESTORE RATE
	1464			
	1465		Are we in hold now run if yes, hold if not	
1516 06 6D 3E	1466	BRSET 3, PSTAT1, RUN		; IF IN START MODE THEN DO RUN
	1467			
1519 00 6D 3B	1468	BRSET 0, PSTAT1, RUN		; IF YES GO RUN
151C 10 6D	1469	HOLD BSET 0, PSTAT1		; IF NOT SET HOLD FLAG
151E 1B 01	1470	BCIR 5, PORTB		; MOTOR OFF
1520 13 6D	1471	BCIR 1, PSTAT1		; CLEAR MOTOR ON FLAG
	1472			
1522 B6 02	1473	LDA PORTC		; RE-INITIALIZE RATE KNOB
1524 A4 03	1474	AND #03		
1526 B7 82	1475	STA ISTRAT		

```

1476 ;
1477 CLR PSTAT2
1478 CLR DOSER ;CLR DOSE ERROR FLAG
1479 JSR UPDATE ;RESTORE DIGITS TO KILL SCROLLING DP
1480 JSR TIMRST
1481 NOHOLD RTS
1482 ;
1483 ; Hold button not down so reset the flag and return
1484 ;
1485 NOH1 BCLR 0,HTEST
1486 RTS
1487 ;
1488 ; LOW BAT HOLD
1489 ;
1490 ; kill motor
1491 ;
1492 HIDEAT BCLR 1,PSTAT1 ;CLEAR MOTOR ON FLAG
1493 BCLR 5,PORTB ;TURN MOTOR OFF
1494 BSET 0,PSTAT1 ;SET HOLD FLAG
1495 ;
1496 ; AND
1497 ;

```



```

1498 ; Kill the audio
1499 ;
1500 NOAUDIO BCIR 5,AIRM ;RESET BEEPER FLAG
1501 BCIR 7,PORIB ;STOP AUDIO NOW
1502 RTS
1503 ;
1504 ; STOP DOSE DELIVIERED MESSAGE
1505 ;
1506 STDOSE BCIR 6,VOIM ;CLEAR ALARM FLAG
1507 BCIR 7,PORIB ;STOP ALARM
1508 BRA HOLD ;PUT PUMP IN HOLD
1509 ;
1510 ; Recovery from error KILL THE MESSAGE
1511 ;
1512 NOVOIM BCIR 6,VOIM
1513 BRA HOLD
1514 ;
1515 NODOS BCIR 0,DFLAG
1516 BRA HOLD
1517 ;
1518 ;
1519 NOMESS CLR PSTAT2

153C 1B 6E
153E 1F 01
1540 81

1541 1D 6E
1543 1F 01
1545 20 D5

1547 1D 6E
1549 20 D1

154B 11 71
154D 20 CD

154F 3F 6E

```

```

1551 CD 1756      JSR  UPDATE      ;RESTORE DISPLAY TO RATE
1554 CC 1557      JMP  RUN          ;GO RUN MOTOR
1522             ;
1523             ;
1524             ;
1525             ;----- RUN MOTOR PUMPING -----
1526             ;
1527             ;
1528             RUN  BCIR 3,PSTAT1  ;SET UNIT START OFF
1529             BSET 4,PSTAT1      ;SET DISPLAY ON
1530             ;
1531             LDA  DS1             ;CHECK IF DOSE DEL BEFORE TURNING
1532             ORA  DS2             ;MOTOR ON
1533             BEQ  RUN1            ;IF DOSE = 0, NO NEED TO CHECK
1534             JSR  CPVTOD          ;ELSE, CALL CMP VOL TO DOSE ROUTINE
1535             CPX  #$FF            ;X IS FF IF VOL >= DOSE
1536             BNE  RUN1            ;IF X != FF, OK TO START MOTOR
1537             ;
1538             BSET 0,DOSER          ;ELSE, SET DOSE DEL MESSAGE
1539             BSET 0,PSTAT1        ;SET HOLD FLAG TO DISABLE MOTCK
1540             BSET 7,ERRON         ;ENABLE ERROR FLAG
1541             BSET 5,ALRM          ;ENABLE ALARM

```

1570 1D 6E	1542	BCLR 6, VOIM	;CLEAR VOL MODE FLAG
1572 11 71	1543	BCLR 0, DFLAG	;CLEAR DOSE MODE FLAG
1574 19 6E	1544	BCLR 4, NOSET	;CLR NO SET FLAG
1576 81	1545	RTS	
	1546		;
	1547		;
1577 3F 7D	1548	RUN1 CLR MOTIM1	
1579 3F 7E	1549	CLR MOTIM2	
157B 3F 81	1550	CLR COUNT4	
157D 3F 63	1551	CLR COUNT2	
157F 3F 5B	1552	CLR REG1	
1581 3F 5D	1553	CLR DRCNT1	
1583 3F 5E	1554	CLR DRCNT2	
1585 3F 5F	1555	CLR REG3	
1587 3F 60	1556	CLR REG4	
1589 3F 61	1557	CLR REG5	
158B 3F 7A	1558	CLR THIRDR1	
158D 3F 7B	1559	CLR THIRDR	
158F 3F 7F	1560	CLR ERRCNT	
1591 3F 6E	1561	CLR PSTAT2	
	1562	LDA #\$10	;
	1563	STA PSTAT2	;

```
1564 ;
1565 LDA DSPDG1 ;CHECK RATE VALUE
1566 ORA DSPDG2
1567 ORA DSPDG3
1568 ORA DSPDG4
1569 BNE RUNMOT IF RATE!=0, RUNMOT
1570 ; BSET 7,ERRON ;IT =000 SO SET ERROR BIT
1571 BSET 5,ALRM ;SET ALARM BIT
1572 BSET 0,PSTAT1
1573 ; BCLR 0,PSTAT1
1574 RTS ;AND RETURN
1575 RUNMOT BSET 1,PSTAT1 ;MOTOR ON FLAG
1576 BCLR 0,PSTAT1 ;RUN FLAG ON
1577 BSET 5,POR1B ;MOTOR ON
1578 RTS
1579 ;
1580
1581
1582 $EJECT
```

7593
S
7593

```

1583 ; DOSE CHECK
1584 ; -----
1585 ; Conditions
1586 ;
1587 DOSECK BRCIR 2,PSTAT1,NDOSE ;DON'T DO IF UNIT IS OFF
1588 BRSET 0,DSPTST,NDOSE ;DON'T DO IF TEST MODE
1589 BRCIR 7,PSTAT1,NDOSE ;DON'T DO IF UNIT IS 224
1590 BRSET 7,PSTAT2,NDOSE ;DON'T DO IF ERROR MODE ON
1591 ;
1592 BRSET 0,DFLAG,DOS1 ;IF DOSE FLAG SET THEN DOS1
1593 ;
1594 BRSET 0,CWF,NDOSE ;IF INC OR DEC FLAG PRESSED
1595 BRSET 0,CCWF,NDOSE ;DONT SET UP DOSE FEATURE
1596 ;
1597 BRCIR 1,PORTD,SETDOS ;IF DOSE BUTTON PUSHED THEN
1598 ;INITIALIZE DOSE MODE
1599 RTS ;ELSE RETURN
1600 ;
1601 DOS1 INC DOSECT
1602 LDA DOSECT
1603 CMP #30
1604 BHI DOS2

```

```

15CA CD 14D7      JSR  DOSTST
15CD 81           NDOSE RTS
1605             ;
1606             SETDOS      BSET 0,DFLAG      ;SET DOSE MODE FLAG
1607             BCIR 6,VOLM      ;CLEAR VOLUME FLAG
1608             ;
1609             BRCLR 0,PSTAT1,CONDO      ;IF PUMP IN HOLD,
1610             BSET 3,PSTAT1      ;SET START FLAG TO DISABLE FLASH
1611             BSET 4,PSTAT1      ;MAKE DISPLAY ON
1612             ;ELSE, JUST CONTINUE WITH DOSE
1613             CONDO CLR  DOSECT      ;CLEAR DOSE COUNTER
1614             BRA  DOS1      ;CONTINUE DOSE HANDLING
1615             ;
1616             DOS2 JSR  DSEXP
1617             LDA  DOSECT
1618             CMP  #120
1619             BLO  NDOSE
1620             JSR  UPDATE
1621             BCIR 0,DFLAG      ;NO DOSE MODE
1622             CLR  DOSECT
1623             RTS
1624             ;
1625             ;
1626
15D2 01 6D 04
15D5 16 6D
15D7 18 6D
15D9 3F 57
15DB 20 E5
15DD CD 1745
15E0 B6 57
15E2 A1 78
15E4 25 E7
15E6 CD 1756
15E9 11 71
15EB 3F 57
15ED 81

```

\$EJECT

1627

```

1628 ;
1629 ; VOLUME DISPLAY CHECK
1630 ;-----
1631 ; Conditions
1632 ;
1633 VOLDIS BRCIR 2,PSTAT1,NVL ;DONT DO IF OFF
1634 BRSET 0,DSPTST,NVL ;DONT DO IF IN TEST MODE
1635 BRCIR 7,PSTAT1,NVL ;DONT DO IF MODEL 224
1636 ; BRSET 0,DFLAG,NVL ;DON'T DO IF IN DOSE MODE
1637 BRSET 7,ERRON,NVL ;DON'T DO IF ERROR MODE
1638 BRSET 0,CWF,NVL ;DONT DO IF INC OR DEC BUTTON
1639 BRSET 0,CCWF,NVL ;IS PRESSED
1640 ;
1641 LDA VS1 ;UPDATE CLEAR VOLUME LED.
1642 ORA VS2
1643 BEQ NOVLED
1644 BCIR 6,PORTB ;TURN VOLUME LED OFF IF VOLUME NOT ZERO
1645 BRA VOLBUT1
1646 NOVLED BSET 6,PORTB ;IF NO VOLUME TURN ON LED
1647 ;
1648 VOLBUT1 BRSET 6,VOLM,VOL1 ;IF VOL FLAG SET UPDATE DISPLAY
1649 BRCIR 3,PORTD,SETVOL ;IF VOL BUTTON PUSHED, INITIALIZE DISPLAY

```



```

1612 81          RTS
1650
1651          ;
1652          SETVOL      BSET 6,VOLM      ;SET VOLUME DISPLAY MODE FLAG
1653          BCIR 0,DFLAG      ;CLEAR DOSE FLAG
1654          CIR  VOLTIM      ;CLEAR VOLUME TIMER
1655          BRCIR 0,PSTAT1,VOL1      ;IF PUMP IN HOLD MODE,
1656          BSET 3,PSTAT1      ;SET START FLAG TO DISABLE FLASH
1657          BSET 4,PSTAT1      ;MAKE DISPLAY ON
1658          ;ELSE, JUST CONTINUE VOLUME
1659          ;
1660          VOL1 INC  VOLTIM      ;INCREMENT VOLTIM
1661          LDA  VOLTIM
1662          CMP  #30      ;IF ELAPSED TIME IS
1663          BHI  VOL2      ; > 1.00 S, DISPLAY VOLUME
1664          JSR  VOLTST      ;ELSE DISPLAY VOLTST
1665          BSET 0,VFLAG      ;SET VOL TEST DISPLAY FLAG
1666          NVL  RTS
1667          ;
1668          VOL2 CMP  #120      ;CHECK ELAPSED TIME, ACCA LOADED
1669          ;WITH VOLTIM IN VOL1 ROUTINE
1670          BHI  ENDVOL      ;IF TIME > 5 SEC, END VOL MODE
1671          ;

```

```
1632 11 75      BC1R 0,VFLAG      ;CLEAR VOL TEST DISPLAY FLAG
1672
1673      ;
1674      VSEXP LDX #VS1      ;SET POINTER TO VS1 ADDRESS
1675      JSR BCDEXP
1676      RTS
1677      ;
1678      ENDVOL      JSR UPDATE      ;RETURN DISPLAY TO RATE
1679      BC1R 6,VOLM
1680      RTS
1681      ;
1682      ;
1683      ;
1684      ;
1685      $EJECT
```

```

1686 ;
1687 ;
1688 ;
1689 ; CHECK CLEAR VOLUME BUTTON
1690 ; -----
1691 ; Conditions
1692 ;
1693 CKCLR BRCLR 2,PSTAT1,NOCLR ;DONT DO IF OFF
1694 BRSET 0,DSPTST,NOCLR ;DONT DO IF IN TEST MODE
1695 BRCLR 7,PSTAT1,NOCLR ;DONT DO IF MODEL 224
1696 BRSET 0,CKBEP,CNALRM ;IF ALARM ALREADY SET, HANDLE BEEP
1697 ;
1698 ; Has volume clr button been pressed
1699 ;
1700 CLR BRSET 4,PORTD,NC1R1 ;IF CLR BUTTON NOT PRESSED RETURN
1701 ;
1702 ; DEBOUNCE SWITCH
1703 BRSET 1,HTEST,NOCLR ;IF BUTTON SENSED LAST CYCLE, MUST BE
1704 ; SAME PULSE SO IGNORE
1705 BSET 1,HTEST ;ELSE SET FLAG FOR NEXT CYCLE
1706 ;
1707 BRCLR 6,VOLM,NOCLR ;IF NOT VOLUME MODE, RETURN

```

```

1708 ;
1657 B6 79 LDA VOLTIM ;CHECK VOLTIM
1709 ;
1659 A1 1F CMP #31 ;IF 'VOL' DISPLAY STILL ON
1710 ;
165B 23 26 BLS NOCLR ;DON'T CLEAR YET
1711 ;
1712 ;
1713 ; CHECK IF OK TO CLEAR VOLUME
1714 ;
1715 ;IF DOSE = 0, CONTINUE CLEAR
165D B6 55 LDA DS1
1716 ORA DS2
165F BA 56 BEQ CLR1
1717 ;
1718 ;
1719 ;IF DOSE != 0 AND DOSE DEL.,
1663 CD 1951 JSR CPVTOD
1720 CPX #$FF
1666 A3 FF BEQ CLR1
1721 ;IF X = FF, CONTINUE WITH CLEAR VOL
1722 ;ELSE, ENABLE SHORT ALARM
1723 CKALRM BSET 0,CKBEP ;SET CHECK ALARM BIT TO ENABLE BEEP
1724 CLR CKTIM ;INITIALIZE BEEP TIME
166A 10 83 BSET 7,PORTB ;TURN ON ALARM
1725 ;
1726 ;
1727 CNAIRM INC CKTIM ;INCREMENT BEEP TIMER
1670 3C 84 LDA CKTIM ;CHECK IF TIME TO STOP BEEP
1728 CMP #$05
1674 A1 05

```

1676 25 04	1730	BLO CONBP	;IF CKTIM < AA, CONTINUE BEEP
1678 1F 01	1731	BCLR 7,PORTB	;ELSE, TURN OFF BEEP
167A 11 83	1732	BCLR 0,CKBEP	;CLEAR CK BEEP FLAG
167C 81	1733	CONBP RTS	
	1734	;	
	1735	;	CLEAR VOLUME
	1736	;	
167D CD 1941	1737	CIR1 JSR CLVOL	;CLEAR VOLUME
1680 CC 1634	1738	JMP VSEXP	
	1739	;	
1683 81	1740	NOCIR RTS	
	1741	;	
1684 13 73	1742	NCIR1 BCLR 1,HTEST	
1686 81	1743	RTS	
	1744	;	
	1745	\$EJECT	

```

1746 ;
1747
1748 ;
1749 ;
1750 ;      Inputting the rate (model 324)
1751 ;      -----
1752 ;
1753 ;      Conditions
1754 ;
1687 05 6D 23 INRATE2  BRCLR 2,PSTAT1,OVER1  ;IF OFF DONT DO
168A 00 6E 20  BRSET 0,LOWBAT,OVER1  ;DONT DO IF LOWBAT
168D 0E 6E 1D  BRSET 7,ERRON,OVER1  ;DONT DO IF ERROR MODE
1690 0F 6D 1A  BRCLR 7,PSTAT1,OVER1  ;IF MODEL 224 DONT DO
1693 00 80 17  BRSET 0,DSPIST,OVER1  ;DONT DO IF IN TEST MODE
1696 0C 6E 14  BRSET 6,VOLM,OVER1  ;DONT DO IF IN VOLUME DISPLAY
1699 06 6D 03  BRSET 3,PSTAT1,CRIE  ;IF IN START MODE DO NOW
169C 01 6D 0E  BRCLR 0,PSTAT1,OVER1  ;DON'T DO IN RUN MODE
1763 ;
1764 ;      Check for rate change
1765 ;
169F 03 02 12  CRIE  BRCLR 1,PORTC,CCW1  ;IF BUTTION DOWN DO DECREASE
16A2 3F 77  CLR  CCWF  ;CLEAR FLAG IF NOT DOWN

```

```

16A4 01 02 07      1768      BRCLR 0,PORTC,CW1 ;IF BUTTON DOWN GO INCREASE
16A7 3F 76         1769      CLR   CWF      ;CLEAR FLAG IF NOT DOWN
16A9 3F 78         1770      CLR   SPEED1
16AB 3F 7C         1771      CLR   OUTSPD
16AD 81            1772      OVERL RTS      ;RETURN IF NO BUTTONS DOWN
1773      ;
1774      ;      Set flag to increase the rate
1775      ;
1776      1776      BSET 0,CWF      ;SET FLAG FOR RATE INCREASE
1777      1777      JSR  SPEED      ;GO GET SPEED AND UPDATE
1778      1778      RTS
1779      ;
1780      ;      Set flag to decrease the rate
1781      ;
1782      1782      CCW1 BSET 0,CCWF      ;SET FLAG FOR RATE DECREASE
1783      1783      JSR  SPEED      ;GO SET SPEED AND UPDATE
1784      1784      RTS
1785      ;
1786      ;      Speed control for touch panel
1787      ;
1788      1788      SPEED INC SPEED1
1789      1789      LDA  SPEED1

```

```

16BE A1 40      1790      CMP    #$40      ;WAIT 1.98 SEC
16C0 23 0A      1791      BLS    SPD1      ;AT FIRST SPEED
16C2 A1 90      1792      CMP    #$90      ;WAIT 3.465 SEC
16C4 23 15      1793      BLS    SPD2
16C6 A6 F0      1794      LDA    #$F0
16C8 B7 78      1795      STA    SPEED1
16CA 20 21      1796      BRA    SPD4
                1797      ;
                1798      ;      Speed 1
                1799      ;
16CC 3C 7C      1800      SPD1 INC OUTSPD
16CE B6 7C      1801      LDA    OUTSPD
16D0 A1 0F      1802      CMP    #$0F      ;CHANGE EVERY .495 SEC
16D2 27 19      1803      BEQ    SPD4
16D4 B6 78      1804      LDA    SPEED1      ;EXCEPT FIRST TIME THROUGH
16D6 A1 01      1805      CMP    #$01
16D8 27 13      1806      BEQ    SPD4
16DA 81         1807      RTS
                1808      ;
                1809      ;      Speed 2
                1810      ;
16DB 3C 7C      1811      SPD2 INC OUTSPD

```



```

16DD B6 7C      1812      LDA      OUTSPD
16DF A1 06      1813      CMP      #$06      ;CHANGE EVERY .198 SEC
16E1 27 0A      1814      BEQ      SPD4
16E3 81         1815      RTS
1816      ;
1817      ;      Speed 3
1818      ;
16E4 3C 7C      1819      SPD3 INC      OUTSPD
16E6 B6 7C      1820      LDA      OUTSPD
16E8 A1 05      1821      CMP      #$05
16EA 27 01      1822      BEQ      SPD4
16EC 81         1823      RTS
1824      ;
16ED 3F 7C      1825      SPD4 CLR      OUTSPD
16EF 16 6D      1826      BSET 3,PSTAT1      ;MAKE START ON
16F1 18 6D      1827      BSET 4,PSTAT1      ;TURN DISPLAY ON
16F3 00 77 06   1828      BRSET 0,CCWF,DECI      ;IF CCW FLAG SET DEC DOSE OR RATE
1829      ;      ;ELSE INCREASE DOSE OR RATE
1830      ;      INCREASE
1831      ;
16F6 00 71 09   1832      BRSET 0,DFLAG,INCR1D      ;IF DOSE, INCREMENT DOSE
16F9 CC 131E    1833      JMP      INCRI      ;ELSE, INCREMENT RATE

```

SDOCID: <EP_____0327209A2_I_>

171B B7 55	1856	STA DS1	
171D B6 56	1857	LDA DS2	
171F A9 00	1858	ADC #500	;BINARY ADD CARRY
1721 8D	1859	DAA	;CONVERT TO BCD
1722 B7 56	1860	STA DS2	
1724 CC 1745	1861	JMP DSEXP	; UPDATE DOSE
	1862		
	1863		
	1864		
1727 B6 57	1865	DECRID LDA DOSECT	;DELAY INC TO ALLOW DOSE DISPLAY
1729 A1 1F	1866	CMP #31	
172B 23 1D	1867	BLS NODOSE	;RETURN FROM INC
172D A6 3D	1868	LDA #61	;RESET DOSE TIMER
172F B7 57	1869	STA DOSECT	;EACH TIME BUTTON IS PUSHED
	1870		
1731 B6 55	1871	LDA DS1	;IF DOSE IS 0 DONT DECREMENT
1733 BA 56	1872	ORA DS2	
1735 27 13	1873	BEQ NODOSE	
	1874		
	1875		
1737 B6 55	1876	LDA DS1	
1739 AB 95	1877	ADD #95	;10 COMPLIMENT BINARY SUBTRACT

ISDOCID: <EP_____0327209A2_I_>

```

1900 ;
1901 ;
1902 ;      Update the digit numbers
1903 ;
1904 ;
1905      UPDATE      LDX      DSPDG1
1906                  LDA DIGITS,X
1907      STA  SAMPL4
1908      LDX  DSPDG2
1909      LDA  DIGITS,X
1910      STA  SAMPL3
1911      LDX  DSPDG3
1912      LDA  DIGITS,X
1913      STA  SAMPL2
1914      LDX  DSPDG4
1915      LDA  DIGITS,X
1916      STA  SAMPL1
1917      ;CHECK THIS CODE FOR HANDLING ZEROST FLAG
1918 ;
1919      BCLR 6,ZEROST      ;INITIALIZE ZEROST
1920      BCLR 7,ZEROST      ;AND
1921      CLR  COUNT3      ;COUNT3 FOR LED MUX ROUTINE

```

```
1922
1923 ;
1924 CLR HLDIM1 ;CLEAR HLDIM1 AND HLDIM2
1925 CLR HLDIM2 ;TO RESTART 2 1/2 MIN TIMER
1926 ;EACH TIME DISPLAY IS UPDATED
1927 ;
1928 ;
1929 ;
1930 ;
1931 CLR QH
1932 CLR PH
1933 LDA #10
1934 STA QL
1935 LDA DSPDG2
1936 STA PL
1937 JSR MULT16
1938 LDA DSPDG1
1939 ADD QL
1940 STA ALGO
1941 LDA #100
1942 STA QL
1943 LDA DSPDG3
```

CALCULATE MOTOR TIMES

```
1778 3F 4B
177A 3F 4C
177C 3F 67
177E 3F 69
1780 A6 0A
1782 B7 68
1784 B6 52
1786 B7 6A
1788 CD 196F
178B B6 51
178D BB 68
178F B7 46
1791 A6 64
1793 B7 68
1795 B6 53
```

1797 B7 6A	1944	STA PL
1799 CD 196F	1945	JSR MULT16
179C B6 46	1946	LDA ALGO
179E B7 6A	1947	STA PL
17A0 CD 1962	1948	JSR ADD16
17A3 B6 67	1949	LDA QH
17A5 B7 69	1950	STA PH
17A7 B6 68	1951	LDA QL
17A9 B7 6A	1952	STA PL
17AB A6 D6	1953	LDA #\$D6
17AD B7 67	1954	STA QH
17AF A6 E8	1955	LDA #\$E8
17B1 B7 68	1956	STA QL
17B3 CD 1993	1957	JSR DIV16
17B6 B6 53	1958	LDA DSPDG3
17B8 26 09	1959	BNE MULT3
17BA B6 65	1960	LDA XH
17BC B7 48	1961	STA TIMHI
17BE B6 66	1962	LDA XL
17C0 B7 47	1963	STA TIMLO
17C2 81	1964	RTS
	1965	;

17C3 B6 65	1966	MULT3	IDA	XH
17C5 B7 67	1967	STA	QH	
17C7 B6 66	1968	IDA	XL	
17C9 B7 68	1969	STA	QL	
17CB A6 03	1970	IDA	#3	
17CD B7 6A	1971	STA	PL	
17CF 3F 69	1972	CIR	PH	
17D1 CD 196F	1973	JSR	MULT16	
17D4 B6 68	1974	IDA	QL	
17D6 B7 47	1975	STA	TIMIO	
17D8 B6 67	1976	IDA	QH	
17DA B7 48	1977	STA	TIMHI	
17DC 81	1978	RTS		
	1979	:		
	1980	:		
	1981	\$EJECT		


```

1982 ;
1983 ;
1984 ; AC OR DC CHECK
1985 ; -----
1986 ;
1987 ACDC BRCIR 6,PORTC,AC ;IF CLR ITS AC
1988 BCLR 1,ACON ;IF NOT CLEAR THE FLAG
1989 RTS
1990 AC BSET 1,ACON ;SET FLAG ITS AC
1991 ; CLR T25 ;RESET TIMER FOR AUTO OFF
1992 ; CLR T20
1993 RTS
1994 ;
1995 $EJECT

```

```

1996 ;
1997 ;
1998 ;          BATTERY CHECK
1999 ;-----
2000 ;
2001 17E6 02 6E 37 BATCK BRSET 1,ACON,NOLOB ;IF ON AC DONT DO
2002 17E9 00 80 45 BRSET 0,DSPTST,NLB ;DONT DO IF TEST MODE
2003 17EC 00 6E 1D BRSET 0,LOWBAT,IBTM ;IF LOW ALREADY TIME 15 MIN.
2004 17EF 03 6D 07 BRCIR 1,PSTAT1,LOBCK ;IF MOTOR OFF CHECK
2005 17F2 B6 5B LDA REG1 ;WAIT UNTILL MOTOR RUNS .4 SEC
2006 17F4 A1 1E CMP #30
2007 17F6 22 01 BHI LOBCK
2008 17F8 81 RTS
2009 17F9 08 02 35 LOBCK BRSET 4,PORTC,NLB ;IF NO SIGNAL THEN LOW BAT
2010 17FC 05 6D 1A BRCIR 2,PSTAT1,KILTIM ;IF PUMP IS OFF, DISABLE PUMP
2011 17FF 10 6E BSET 0,LOWBAT ;SET LOW BAT FLAG
2012 1801 1E 6E BSET 7,ERRON ;SET ERROR
2013 1803 1A 6E BSET 5,AIRM ;SET ALARM
2014 1805 17 6D BCIR 3,PSTAT1 ;GET OUT OF START MODE TO ENABLE LOW BAT
2015 1807 11 71 BCIR 0,DFLAG ;CLEAR DOSE MODE FLAG
2016 1809 1D 6E BCIR 6,VOLM ;CLEAR VOLUME MODE FLAG
2017 180B 81 RTS

```

```

2018 ;
2019 ; INCREMENT 15 MIN TIMER
2020 ;
2021 LBIM INC BATTM1 ;INCREMENT BATTERY TIMER: BATTM1,BATTM2
2022 BNE CONCNT
2023 INC BATTM2
2024 CONCNT LDA BATTM2
2025 CMP #$07 ;IF BAT TIMER HAS COUNTED 15 MIN
2026 BEQ KILTIM ;KILL POWER
2027 RTS
2028 KILTIM SEI ;SET INT MASK TO PREVENT TURN-ON
2029 LDA #$0F ;DISABLE PUMP
2030 STA PORTB
2031 BRA KILTIM
2032 ;
2033 NOLOB BRCIR 0,LOWBAT,NLB ;DONT CLEAR ANY THING IF NO LOW BAT
2034 ;THIS MAINTAINS OTHER ERRORS IF PRESENT
2035 BCIR 0,LOWBAT ;CLR LOW BAT FLAG
2036 BCIR 7,ERRON ;CLR ERROR FLAG
2037 BCIR 5,ALRM ;CLR ALARM
2038 BSET 4,PSTAT1 ;MAKE SURE DISPLAY ON
2039 JSR UPDATE ;UPDATE DISPLAY

```

SDOCID: <EP_____0327209A2_1_>

```

2049 ;
2050 ;      DEAD BATTERY CHECK
2051 ;
2052 ;      This routine checks the dead battery signal (portc(7)).
2053 ;      If this signal is active (portc(7)=0), then the routine
2054 ;      kills power to the processor.
2055 ;-----
2056 ;
2057 ;      DBATCK      BRSET 1,ACON,NODECK      ;DON'T DO IF AC POWERED
2058 ;      BRCLR 1,PSTAT1,DEADCK ;IF MOTOR OFF CHECK
2059 ;      LDA REG1          ;WAIT UNTILL MOTOR RUNS .4 SEC
2060 ;      CMP #30
2061 ;      BHI DEADCK
2062 ;      RTS
2063 ;
2064 ;      DEADCK BRSET 7,PORTC,NODECK ;IF NO DEAD BAT SIGNAL, RETURN
2065 ;
2066 ;      DBKIL SEI          ;SET INT MASK TO PREVENT TURN-ON
2067 ;      LDA #0F          ;DISABLE PUMP
2068 ;      STA PORTB
2069 ;      BRA DBKIL        ;LOOP UNTIL POWER DISSIPATES
2070 ;

```

	184D 81	2071	2072	2073	NODECK	RTS
					;	
					\$EJECT	

```

2074 ;
2075 ;          ALARM
2076 ;-----
2077 ;          Conditions
2078 ;
184E 05 6D 08      ALARM BRCLR 2,PSTAT1,NOAIM      ;IF OFF DONT ALARM
1851 0C 6E 05      BRSET 6,VOLM,NOAIM              ;IF IN VOLUME DONT DO
1854 0A 6E 03      BRSET 5,ALRM,ALRMRT             ;IF ALARM FLAG SET THEN ALARM
2082 ;
2083 ;
1857 1F 01      ALCIR      BCIR 7,PORTB              ;SET ALARM HIGH
1859 81      NOAIM RTS
185A 08 6D FA      ALRMRT BRSET 4,PSTAT1,ALCIR
185D 1E 01      BSET 7,PORTB
185F 81      RTS
2089 ;
2090 $EJECT

```

↓SDOCID: <EP_____0327209A2_1_>

7593

```

187E 04 6E 50      2113      BRSET 2,NDROP,FLO1      ;IF FLOW ERR THEN DO
1881 00 70 45      2114      BRSET 0,DOSE1,DOSE1      ;IF DOSE ERROR THEN DO
1884 06 6E 46      2115      BRSET 3,HOLDER,HLD1      ;IF HOLD ERROR THEN DO
1887 20 59         2116      BRA ERR1
1889 81            2117      NOBLIN      RTS
2118      ;
2119      ;      Hold mode blink
2120      ;
188A 18 6D         2121      SETBL BSET 4,PSTAT1      ;BLANK DISPLAY
188C 0F 6E FA      2122      BRCLR 7,ERRON,NOBLIN
188F 00 6E 54      2123      BRSET 0,LOWBAT,BAT1      ;GO DO BAT IF LO BAT
1892 08 6E 5E      2124      BRSET 4,NOSET,SET2      ;GO DO SET IF NO SET
1895 04 6E 4A      2125      BRSET 2,NDROP,ERR1      ;GO DO ERR IF FLOW ERR
1898 00 70 26      2126      BRSET 0,DOSE1,OUT2      ;GO DO DEL IF DOSE ERR
189B 06 6E 44      2127      BRSET 3,HOLDER,ERR1      ;GO DO ERR IF HOLD ERR
189E 20 3E         2128      BRA SYS1
18A0 81            2129      RTS
2130      ;
2131      ;      Blink the DP during the run mode
2132      ;
18A1 BE 63         2133      DOTBL LDX COUNT2      ;GET DP #
18A3 E6 4D         2134      LDA SAMPLE1,X      ;GET NEW DIGIT

```

```

18A5 AA 80      2135      ORA    #$80      ;CLEAR DP
18A7 E7 4D      2136      STA    SAMPL1,X  ;STORE IT FOR DISPLAY
18A9 5C         2137      INCX           ;BUMP POINTER TO NEXT DIGIT
18AA A3 04      2138      CPX    #$04      ;DONE ALL THREE
18AC 27 09      2139      BEQ    NEWX      ;RESET IF SO
18AE E6 4D      2140      DOTON LDA SAMPL1,X ;GET NEXT DIGIT
18B0 A4 7F      2141      AND    #$7F      ;TURN DP ON
18B2 E7 4D      2142      STA    SAMPL1,X  ;STORE IT FOR DISPLAY
18B4 BF 63      2143      STX    COUNT2    ;SAVE COUNT
18B6 81         2144      RTS
                ;
18B7 0F 6D 03   2145      NEWX  BRCLR 7,PSTAT1,DOT24 ;IF 224, SCROLL 3 DIGITS
18BA 5F         2146      CLRX           ;RESET COUNTER
18BB 20 F1      2147      BRA    DOTON    ;GO TURN ON
                ;
18BD AE 01      2148      DOT24 LDX  #$01    ;IF THIRD DIGIT
18BF 20 ED      2149      BRA    DOTON    ;ELSE CONTINUE WITH BLINK ROUTINE
                ;
                ;      Error messages
                ;
18C1 A6 8C      2150      OUT2  LDA  #$8C
18C3 B7 4D      2151      STA    SAMPL1
                ;

```

```

2157      ;
18C5 AE 16      LDX    #$16      ;DISPLAY ?
2158
18C7 20 2E      BRA     OUTCHR
2159
2160      ;
18C9 AE 19      DOSE1 LDX    #$19      ;DISPLAY DOSE
2161
18CB 20 2A      BRA     OUTCHR
2162
2163      ;
2164      ;
18CD AE 12      HLD1  LDX    #$12      ;POINT TO ERR MESSAGE
2165
18CF 20 26      BRA     OUTCHR      ;GO LOAD UP DIGITS
2166
2167      ;
18D1 AE 06      FLO1  LDX    #$06      ;POINT TO FLO MESSAGE
2168
18D3 20 22      BRA     OUTCHR      ;GO LOAD UP DIGITS
2169
2170      ;
18D5 AE 00      LO1   LDX    #$00
2171
18D7 CD 18F7     JSR     OUTCHR
2172
18DA 01 6D C4     BRC1R 0,PSTAT1,DOTBL      ;IF IN RUN MODE, UPDATE DP SCROLL
2173
18DD 81          RTS
2174
2175      ;
18DE AE 1C      SYS1  LDX    #$1C      ;DISPLAY SYS
2176
18E0 20 15      BRA     OUTCHR
2177
2178      ;

```

0327209A2

```
2179      ;
2180      ERR1  LDX  #$09
2181      BRA  OUTCHR
2182      ;
2183      BAT1  LDX  #$03
2184      JSR  OUTCHR
2185      BRC1R 0,PSTAT1,DOTBL  ;IF IN RUN MODE, UPDATE DP SCROLL
2186      RTS
2187      ;
2188      NO1   LDX  #$0C
2189      BRA  OUTCHR
2190      ;
2191      SET2  LDX  #$0F
2192      BRA  OUTCHR
2193      ;
2194      OUTCHR  LDA  TABLE5,X
2195      STA  SAMPLE2
2196      INCX
2197      LDA  TABLE5,X
2198      STA  SAMPLE3
2199      INCX
2200      LDA  TABLE5,X
```

1906 B7 50	2201	STA	SAMPL4
1908 81	2202	RTS	
	2203	;	
	2204	\$EJECT	

7593

```

2205 ;
2206 ; HOLD ERROR
2207 ;-----
2208 ; Conditions
2209 ;
2210 HILDER BRCIR 2,PSTAT1,NOHE ;DONT DO IF OFF
2211 BRCIR 0,PSTAT1,NOHE ;DONT DO IF NOT IN HOLD
2212 ;
2213 ; Test for hold error
2214 ;
2215 INC HLDTIM1 ;INCREMENT HOLD COUNTER
2216 BNE CNCNT
2217 INC HLDTIM2
2218 CNCNT LDA HLDTIM2 ;CHECK IF 2 1/2 MIN ELAPSED
2219 CMP #501
2220 BHI HILDER1 ;IF HLDTIM2 > 1, HOLDER
2221 BEQ CONCK ;IF HLDTIM2= 1, CHECK HLDTIM1
2222 RTS ;ELSE RETURN
2223 ;
2224 CONCK LDA HLDTIM1
2225 CMP #27 ;IF HLDTIM1 >= 27, HOLDER
2226 BHS HILDER1

```

```
1924 81      2227      RTS
                2228      ;
1925 17 6D    2229      HLDER1    BCLR 3,PSTAT1    ;CLEAR START FLAG
1927 16 6E    2230      BSET 3,HOLDER    ;SET HOLD ERROR FLAG
1929 1A 6E    2231      BSET 5,ALRM      ;ALARM ON
192B 1E 6E    2232      BSET 7,ERRON     ;ERROR FLAG ON
192D 81      2233      NOHE RTS
                2234      ;
                2235      $EJECT
```

```

2236 ;
2237 ; ONE DAY WAIT FOR AUTO OFF
2238 ;-----
2239 ; Conditions
2240 ;
2241 TIM24 BRSET 2,PSTAT1,KEEPON ;IF UNIT ON DONT DO
2242 ;
2243 ; 24HR TURN OFF
2244 ;
2245 INC T25 ;GET COUNTER
2246 LDA T25
2247 CMP #$EF ;(EF + 1) = 240 x 6 = 24 HOURS
2248 BLO KEEPON
2249 ;
2250 KILLP SEI ;SET INT MASK TO PREVENT TURN-ON
2251 LDA #$0F ;DISABLE PUMP
2252 STA PORTB
2253 BRA KILLP ;LOOP UNTIL POWER DISSAPTES
2254 ;
2255 KEEPON RTS
2256 ;
2257 ;

```



```

2258 ; CLEAR VOLUME SUBROUTINE
2259 ; This routine is called by tim24 and ckclr routines.
2260 ; -----
2261 ;
2262 CLVOL CLR DECML1
2263 CLR VS1
2264 CLR VS2
2265 RTS
2266 ;
2267 ; CLEAR TIMER COUNTERS
2268 ; -----
2269 ;
2270 TIMRST CLR TS
2271 CLR T5
2272 CLR T10
2273 CLR T15
2274 RTS
2275 ; COMPARE DOSE TO VOLUME
2276 ; -----
2277 ;
2278 ; IF VOLUME DELIVERED >= PROGRAMMED DOSE, SET X REGISTOR TO FF
2279 ;

```

```
1951 5F      CPVTOD      CIRX
1952 B6 5A      LDA VS2
1954 B1 56      CMP DS2
1956 25 09      BLO VLTD
1958 22 06      BHI VGTD
                ; IF VOLUME < DOSE, CLEAR C
                ; IF VOLUME > DOSE, SET C
                ; ELSE, CHECK VS1
                ;
195A B6 59      LDA VS1
195C B1 55      CMP DS1
195E 25 01      BLO VLTD
                ; IF VOLUME < DOSE, CLEAR C
                ;
2280          ;
2281          VGTD COMX
2282          VLTD RTS
2283          ;
2284          ;
2285          ;
2286          ;
2287          ;
2288          ;
2289          ;
2290          ;
2291          ;
2292          ;
2293          ;
2294          $EJECT
```

```
2295 ;*****
2296 ;
2297 ;
2298 ; MATH UTILITIES FOLLOW
2299 ;
2300 ;
2301 ;*****
2302 ;
2303 ;
2304 ;*****
2305 ;
2306 ; PROGRAM ADDS 2, 16-BIT UNSIGNED BINARY NUMBERS, PRODUCING A 17-BIT
2307 ; RESULT.
2308 ; ENTER WITH: 2, UNSIGNED 16-BIT OPERANDS TO BE ADDED IN
2309 ; PH , PL and QH , QL.
2310 ; EXIT WITH: 17-BIT RESULT IN: CARRY , QH, QL
2311 ; (QH, QL DESTROYED).
2312 ;
2313 ;*****
2314 ;
2315 ;
2316 ADD16 LDA QL ;ADD 16 BYTES.
```

```

1964 BB 6A      2317      ADD      PL
1966 B7 68      2318      STA      QL
1968 B6 67      2319      LDA      QH      ;ADD MS BYTES.
196A B9 69      2320      ADC      PH
196C B7 67      2321      STA      QH      ;16-BIT RESULT IN QH, QL. OVERFLOW IN CARRY.
                2322      ;
196E 81         2323      RTS
                2324      ;
                2325      ;
                2326      ;
                2327      ;
                2328      ;*****
                2329      ;      *
                2330      ;      PROGRAM MULTIPLIES 2, 16 BIT UNSIGNED BINARY OPERANDS, CREATING A 32--*
                2331      ;      BIT UNSIGNED RESULT. (NO OVERFLOW IS POSSIBLE).      *
                2332      ;      ENTER WITH:  OPERANDS TO BE MULTIPLIED IN:      *
                2333      ;                      QH , QL      *
                2334      ;                      and PH , PL      *
                2335      ;      EXIT WITH:  32-BIT RESULT IN:      XH , XL , QH , QL      *
                2336      ;                      *
                2337      ;*****
                2338      ;

```

```

2339      ;
2340      MULT16 LDX      #16      ;LOOP COUNTER.
2341      CLR      XH      ;CLEAR UPPER 16 BITS OF 32-BIT ACCUM.
2342      CLR      XL
2343      ROR      QH      ;CHECK BIT 0 OF QL.
2344      ROR      QL
2345      NXT      BCC      ROTAT   ;IF 0, DON'T ADD, JUST SHIFT.
2346      LDA      XL      ;OTHERWISE, ADD IN THE CONTENTS OF PH , PL TO
2347      ADD      PL      ;XH , XL.
2348      STA      XL
2349      LDA      XH
2350      ADC      PH
2351      STA      XH
2352      ;
2353      ROTAT      ROR      XH      ;SHIFT THE 32-BIT ACCUM. 1 BIT RIGHT.
2354      ROR      XL
2355      ROR      QH
2356      ROR      QL
2357      ;
2358      DECX
2359      BNE      NXT
2360      ;

```

196F AE 10
1971 3F 65
1973 3F 66
1975 36 67
1977 36 68
1979 24 0C
197B B6 66
197D BB 6A
197F B7 66
1981 B6 65
1983 B9 69
1985 B7 65

1987 36 65
1989 36 66
198B 36 67
198D 36 68

198F 5A
1990 26 E7

```

1992 81      2361      RTS      ;OTHERWISE, RETURN WITH RESULT IN XH,XL,QH,QL.
      2362      ;
      2363      ;
      2364      ;*****
      2365      ;
      2366      ; PROGRAM PERFORMS THE DIVISION OF 2, 16 BIT UNSIGNED OPERANDS, PRODUC-
      2367      ; ING A 16 BIT UNSIGNED RESULT:
      2368      ;
      2369      ; (QH , QL/ PH , PL) -----> XH , XL
      2370      ;
      2371      ; ENTER WITH: 16 BIT DIVISOR IN PH , PL
      2372      ; 16 BIT DIVIDEND IN QH , QL
      2373      ;
      2374      ; EXIT WITH: QUOTIENT TRUNCATED TO 16 BITS
      2375      ; IN XH , XL
      2376      ; REGISTERS AFFECTED: X, A, COUNT1, TEMP, TEMPX
      2377      ; (QH, QL, PH, PL DESTROYED)
      2378      ;
      2379      ;*****
      2380      ;
      2381      ;
      2382      DIV16 LDA #1
1993 A6 01

```

1995 3D 69	2383	TST	PH	
1997 2B 0B	2384	BMI	DIV153	;IF DIVISOR IS LEFT-JUSTIFIED.
1999 4C	2385	DIV151 INCA		;OTHERWISE, KEEP SHIFTING DIVISOR LEFT
199A 38 6A	2386	ASL	PL	;UNTIL THE MSB IN PH = 1, OR UNTIL
199C 39 69	2387	ROL	PH	;16 SHIFTS HAVE BEEN DONE.
199E 2B 04	2388	BMI	DIV153	
19A0 A1 11	2389	CMP	#17	
19A2 26 F5	2390	BNE	DIV151	
19A4 B7 62	2391	STA	COUNT1	;COUNT1 = # SHIFTS REQUIRED +1.
19A6 B6 67	2392	LDA	QH	;MOVE THE DIVIDEND INTO A, X.
19A8 BE 68	2393	LDX	QL	
19AA 3F 67	2394	CIR	QH	;MAKE WAY FOR THE QUOTIENT.
19AC 3F 68	2395	CIR	QL	
19AE BF 6C	2396	STX	TEMPX	;STORAGE FOR THE DIVIDEND AFTER SUBTRACTING
19B0 B7 6B	2397	STA	TEMPA	;OUT DIVISOR.
19B2 9F	2398	TXA		
19B3 B0 6A	2399	SUB	PL	;TRY SUBTRACTING THE DIVISOR.
19B5 B7 6C	2400	STA	TEMPX	
19B7 B6 6B	2401	LDA	TEMPA	;SAVE THE REMAINDER IN TEMPA, TEMPX.
19B9 B2 69	2402	SBC	PH	
19BB B7 6B	2403	STA	TEMPA	
19BD BE 6C	2404	LDX	TEMPX	

19BF 24 10	2405		BCC	DIV165	;IF CARRY=0, THEN DIVISOR WAS SMALLER THAN
	2406				;DIVIDEND. GO SET THE CURRENT QUOTIENT BIT.
	2407				;OTHERWISE, ADD THE DIVISOR BACK IN,
19C1 9F	2408	TXA			
19C2 BB 6A	2409	ADD	PL		
19C4 B7 6C	2410	STA	TEMPX		
19C6 B6 6B	2411	LDA	TEMPA		
19C8 B9 69	2412	ADC	PH		
19CA B7 6B	2413	STA	TEMPA		;AND SAVE IT.
19CC BE 6C	2414	LDX	TEMPX		
19CE 98	2415	CLC			;THE QUOTIENT BIT WILL BE 0.
19CF 20 01	2416	BRA	DIV167		
19D1 99	2417	DIV165 SEC			;THE QUOTIENT BIT WILL BE 1.
19D2 39 68	2418	DIV167 ROL	QL		;ROTATE THE QUOTIENT LEFT 1 BIT,
19D4 39 67	2419	ROL	QH		;SHIFTING THE MOST RECENT QUOTIENT BIT
19D6 34 69	2420	LSR	PH		;INTO THE LSB.
19D8 36 6A	2421	ROR	PL		
19DA 3A 62	2422	DEC	COUNT1		;KEEP GOING UNTIL THE COUNTER=0.
19DC 26 D0	2423	BNE	DIV163		
19DE B6 67	2424	LDA	QH		;WHEN DONE, MOVE THE RESULT INTO XH, XL.
19E0 B7 65	2425	STA	XH		
19E2 B6 68	2426	LDA	QL		


```

19E4 B7 66      2427      STA      XL
                  ;
19E6 81      2428
                2429      RTS      ;RETURN.
                2430
                2431      ;*****
                2432      ;
                2433      ;          BCDEXP
                2434      ;
                2435      ;  PROGRAM CONVERTS 2 BYTE BCD NUMBER POINTED TO BY THE X REGISTER TO *
                2436      ;  A 4 BYTE DECIMAL NUMBER. THE FOUR BYTE NUMBER IS CONVERTED ON THE FLY *
                2437      ;  TO THE CORRECT LED DISPLAY SEGMENT CODE WHICH IS SENT TO THE DISPLAY *
                2438      ;  BY THE LED MUX ROUTINE.
                2439      ;
                2440      ;  ENTER WITH: ADDRESS OF LOWER BCD BYTE IN X
                2441      ;
                2442      ;  EXIT WITH: LED DISPLAY CODE FOR 4 DECIMAL DIGITS
                2443      ;  IN SAMPLE1, SAMPLE2, SAMPLE3, SAMPLE4
                2444      ;
                2445      ;  *
                2446      ;  REGISTERS AFFECTED: X, A, SAMPLE1 - SAMPLE4, TEMPX
                2447      ;
                2448      ;*****

```

```

19E7 BF 6C      2449      BCDEXP      STX  TEMPX      ;STORE POINTER FOR LATER USE
19E9 F6      2450      LDA  ,X      ;GET LOWER BYTE OF BCD DIGIT
19EA A4 0F      2451      AND  #$0F      ;MASK UPPER NIBBLE
19EC 97      2452      TAX
19ED D6 101F    2453      LDA  DIGITS,X  ;CONVERT DECIMAL TO LED CODE
19F0 B7 50      2454      STA  SAMPL4
19F2 BE 6C      2455      ;
19F4 F6      2456      LDX  TEMPX      ;RESTORE FIRST BCD BYTE
19F5 44      2457      LDA  ,X
19F6 44      2458      LSR4
19F7 44      2459      LSR4
19F8 44      2460      LSR4
19F9 97      2461      LSR4
19FA D6 101F    2462      TAX
19FD B7 4F      2463      LDA  DIGITS,X  ;CONVERT DECIMAL TO LED CODE
19FF 3C 6C      2464      STA  SAMPL3
1A01 BE 6C      2465      ;
1A03 F6      2466      INC  TEMPX      ;SET POINTER TO UPPER BCD DIGIT
1A04 A4 0F      2467      LDX  TEMPX      ;GET SECOND BCD DIGIT
1A06 97      2468      LDA  ,X
1A08 97      2469      AND  #$0F      ;MASK UPPER NIBBLE
1A0A 97      2470      TAX

```

```

1A07 D6 101F      2471      LDA  DIGITS,X      ;CONVERT DECIMAL TO LED CODE
1A0A B7 4E         2472      STA  SAMPL2
                    2473      ;
1A0C BE 6C         2474      LDX  TEMPX          ;RESTORE SECOND BCD DIGIT
1A0E F6           2475      LDA  ,X
1A0F 44           2476      LSR  A
1A10 44           2477      LSR  A
1A11 44           2478      LSR  A
1A12 44           2479      LSR  A          ;PUSH UPPER NIBBLE TO LOWER NIBBLE
1A13 97           2480      TAX
1A14 D6 101F      2481      LDA  DIGITS,X      ;CONVERT DECIMAL TO LED CODE
1A17 B7 4D         2482      STA  SAMPL1
                    2483      ;
                    2484      ;      UPDATE DISPLAY FLAGS USED BY LED MUX
                    2485      ;
1A19 1D 74        2486      BCIR  6,ZEROST      ;CLEAR MSD ZERO FLAG
1A1B 1F 74        2487      BCIR  7,ZEROST      ;CLEAR MSD-1 ZERO FLAG
1A1D 3F 64        2488      CIRR  COUNT3        ;CLEAR MUX COUNTER
1A1F 81           2489      RIR
                    2490      ;
                    2491      SEJECT

```

2492			
2493	=1C00	ORG	PMP1ST
2494			
2495	1C00 1E 01	ELOOP BSET	7,PORTB
2496	1C02 20 FC	BRA	ELOOP
2497			;
2498			END

FIG. 1

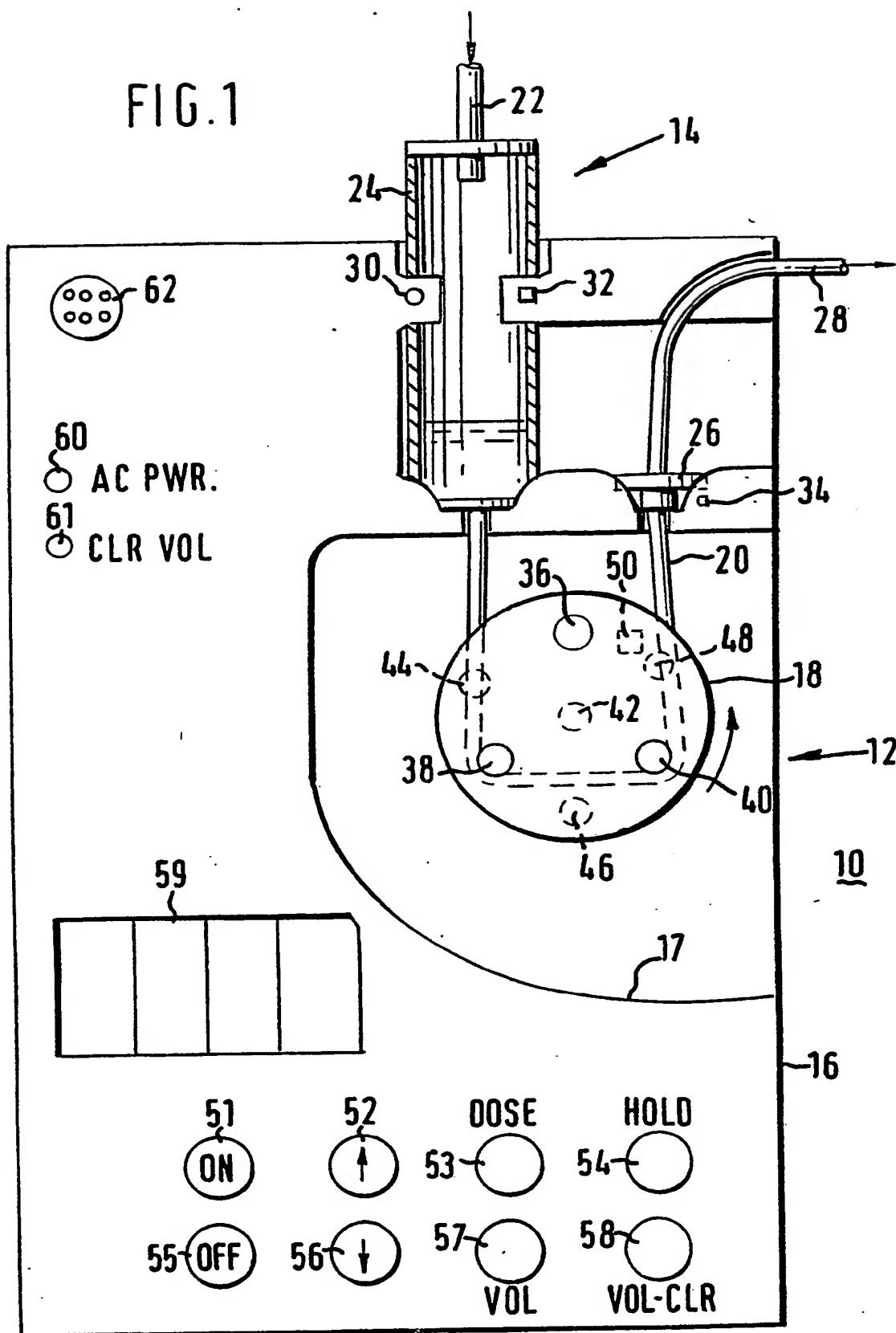


FIG. 2a

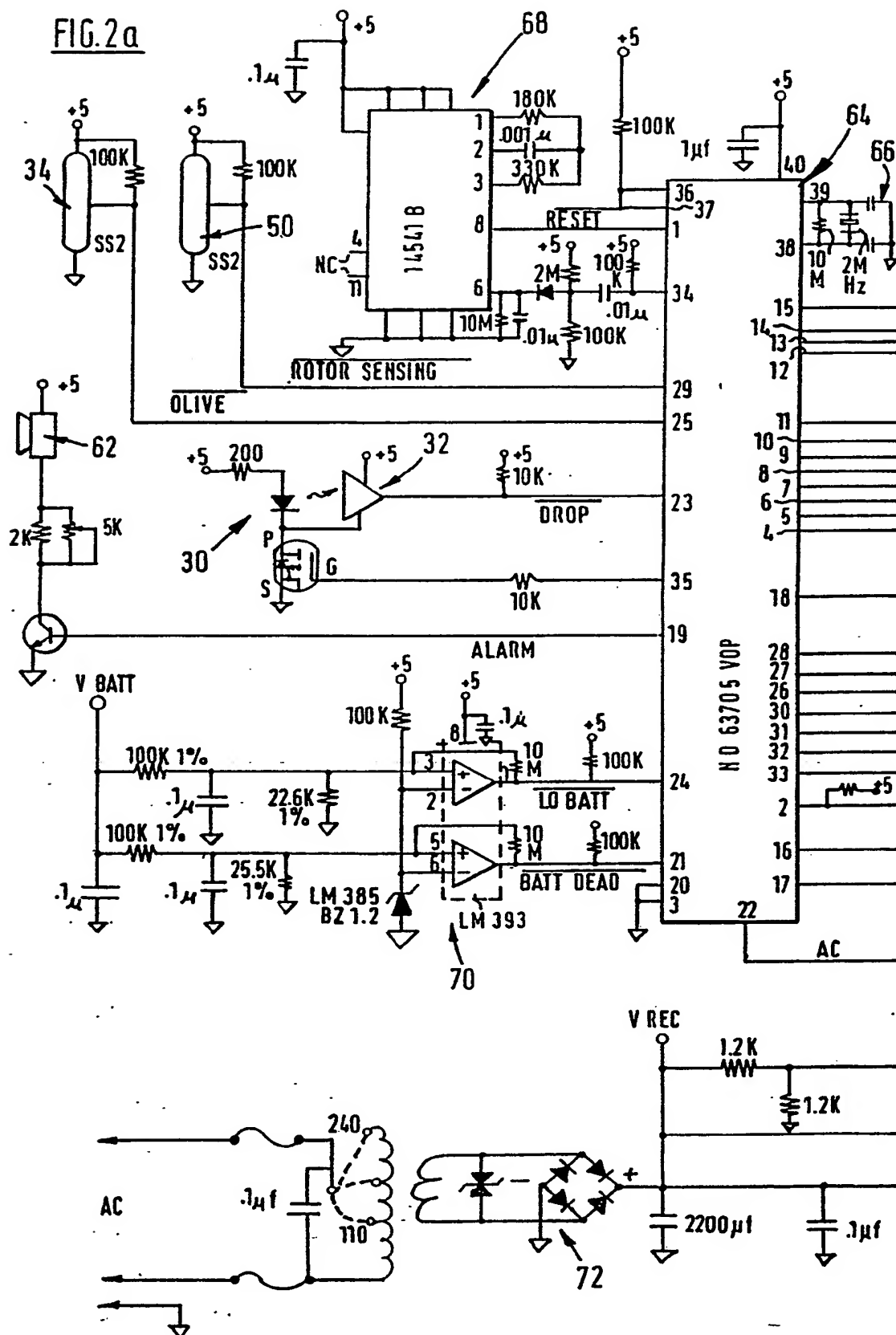
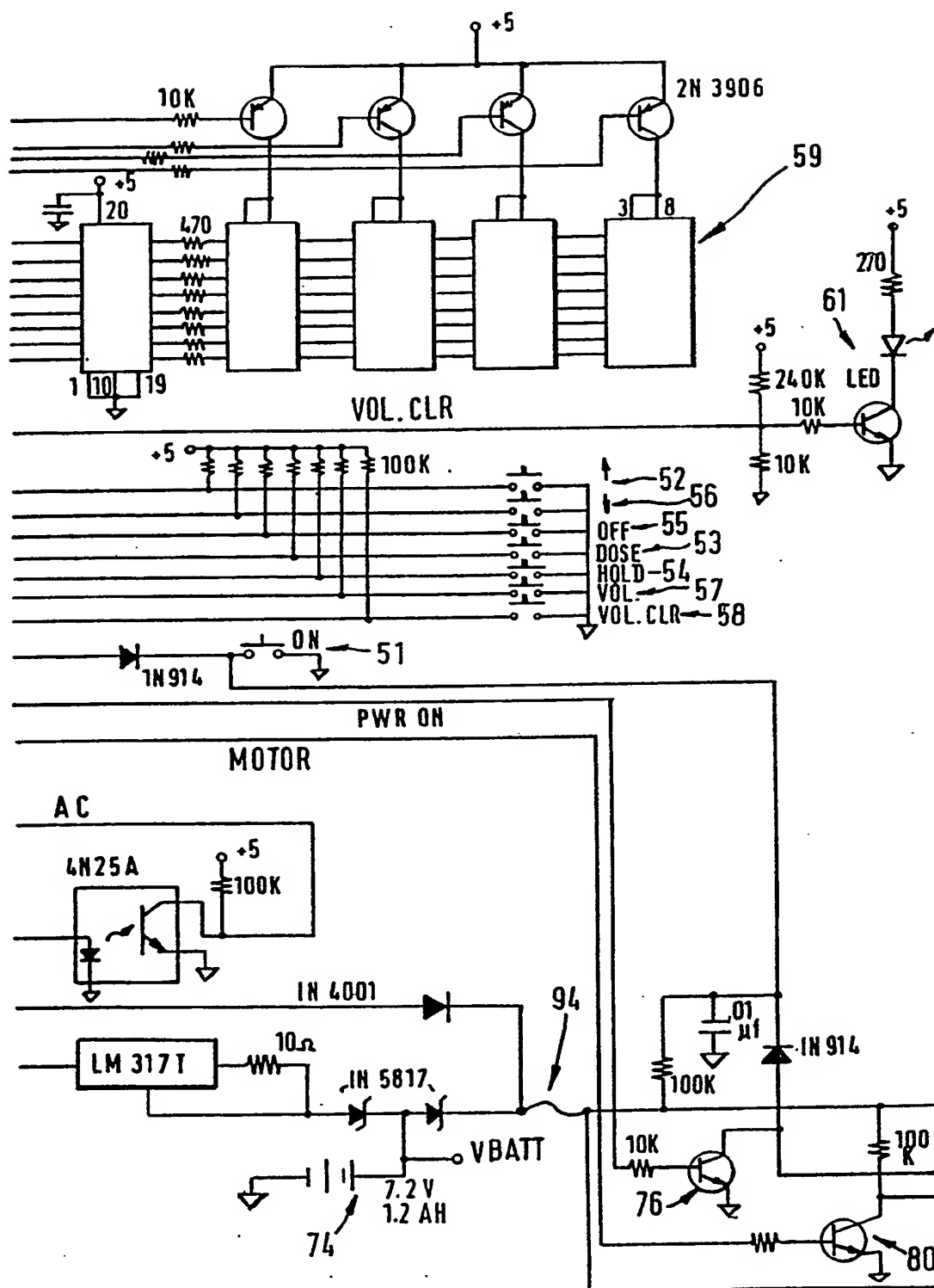


FIG. 2b



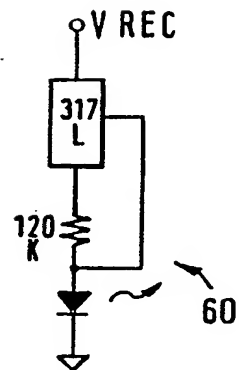
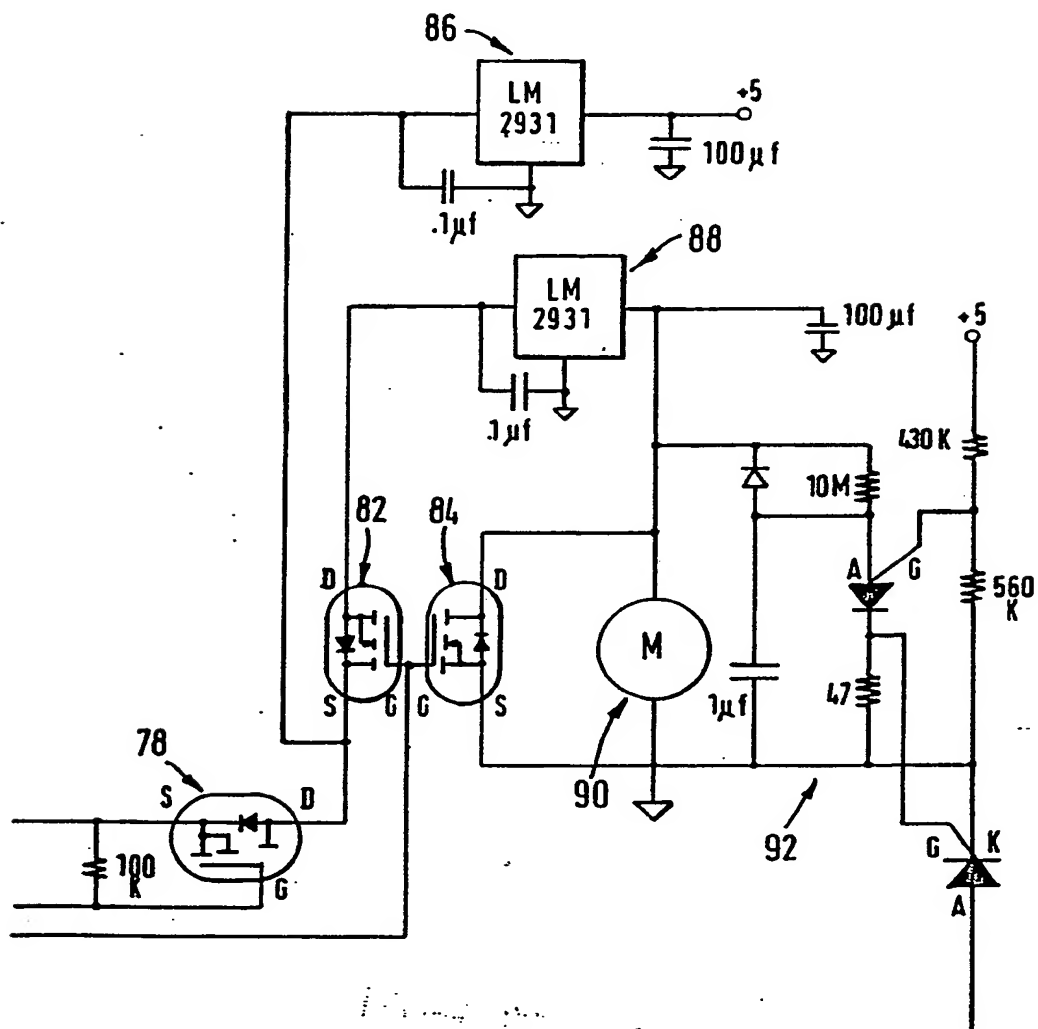


FIG. 2c



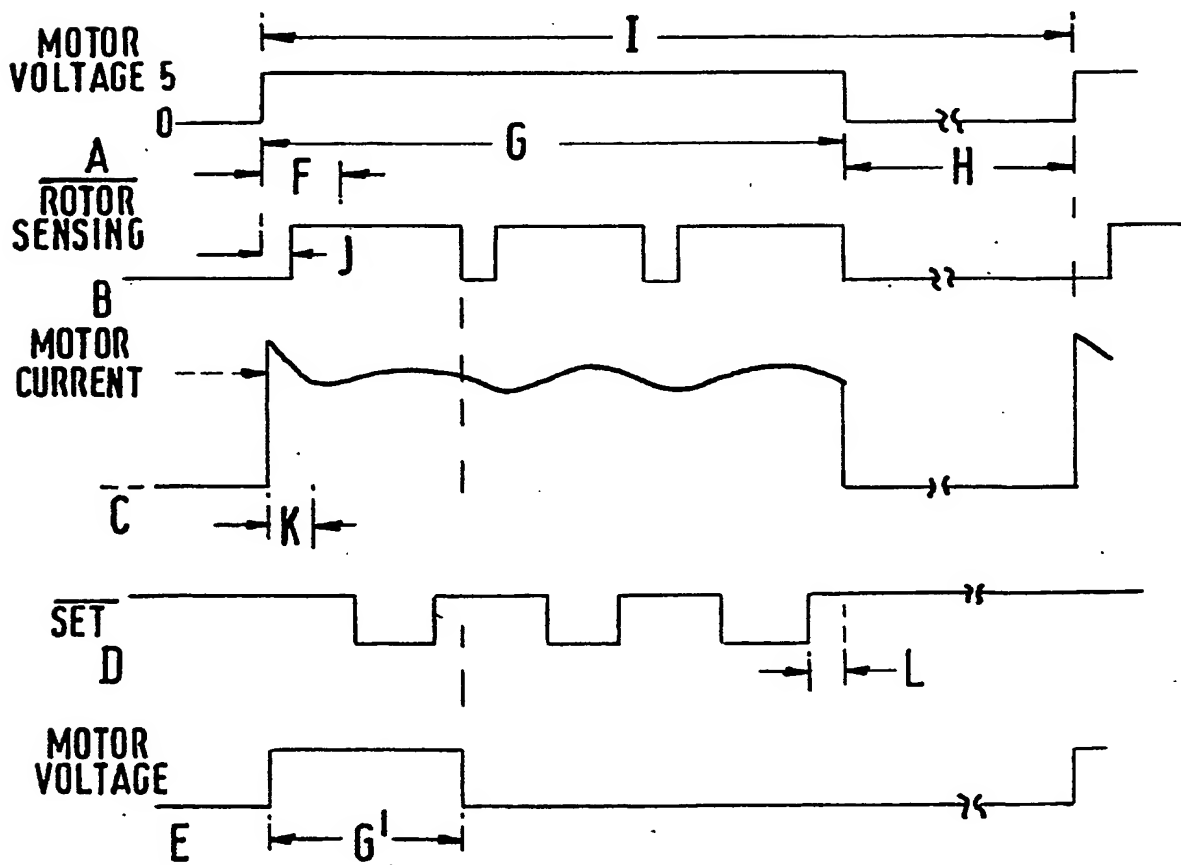
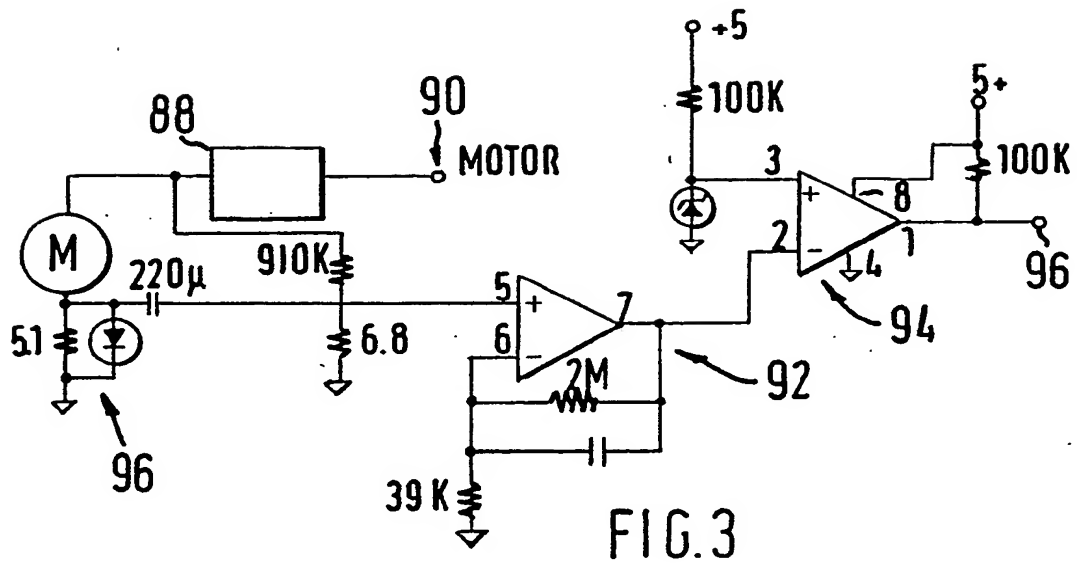


FIG 4

⑫

EUROPEAN PATENT APPLICATION

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F 04 B 51/00

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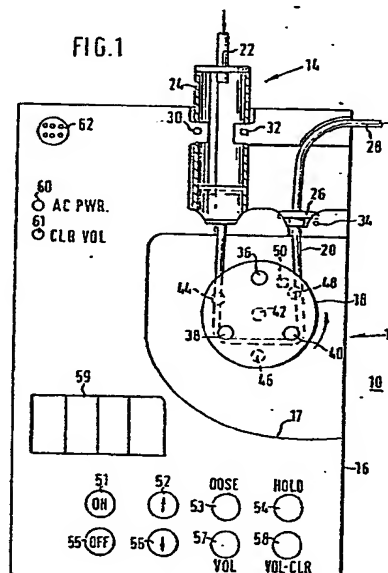
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⑥ Motor unit for a fluid pump and method of operation.

⑦ An enteral nutrition pump system (10) operates in a cyclical manner with a period between cycles being selected in accordance with the desired fluid delivery rate. Each pump cycle may correspond to a single rotation of the rotor (18) or a fractional rotation of the rotor. Rotor rotation may alternatively be sensed by utilization of magnetic sensors (50) or by monitoring of the AC component of current supplied to a DC motor driving the rotor.

FIG.1



Bundesdruckerei Berlin



EP 89 30 0296

DOCUMENTS CONSIDERED TO BE RELEVANT			
Category	Citation of document with indication, where appropriate, of relevant passages	Relevant to claim	CLASSIFICATION OF THE APPLICATION (Int. Cl. 4)
X	DE-A-2 651 962 (SIEMENS AG) * Page 10, line 22 - page 11, line 5, line 25 - page 12, line 15; figure 3 *	1-4,6,8-11	A 61 M 5/14 F 04 B 51/00
Y	--	12	
X	EP-A-0 127 346 (PERITRONIC) * Page 8, line 10 - page 10, line 22 *	1-3,8,9	
Y	--	12	
X	US-A-4 498 843 (SCHNEIDER et al.) * Abstract; column 9, line 44 - column 11, line 34 *	1-3,8,9	
X	WO-A-86 01 413 (SCHWEIZER) * Claims 1-5; abstract *	1-3	TECHNICAL FIELDS SEARCHED (Int. Cl. 4) A 61 M H 02 P F 04 B
X	GB-A-2 011 652 (NIKKISO CO. LTD) * Page 3, lines 36-75 *	1,2	
A	EP-A-0 090 152 (SGS-ATES) * Abstract; figure 4 *	5,7,13	
A	US-A-3 610 779 (HUBBY) * Column 4, line 62 - column 5, line 71; figures 4,5 *	5,7,13,15	
The present search report has been drawn up for all claims			
Place of search THE HAGUE		Date of completion of the search 02-08-1989	Examiner CLARKSON
CATEGORY OF CITED DOCUMENTS			
X : particularly relevant if taken alone Y : particularly relevant if combined with another document of the same category A : technological background O : non-written disclosure P : intermediate document		T : theory or principle underlying the invention E : earlier patent document, but published on, or after the filing date D : document cited in the application L : document cited for other reasons & : member of the same patent family, corresponding document	

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CLAIMS INCURRING FEES

The present European patent application comprised at the time of filing more than ten claims.

- ☐ All claims fees have been paid within the prescribed time limit. The present European search report has been drawn up for all claims.
- ☐ Only part of the claims fees have been paid within the prescribed time limit. The present European search report has been drawn up for the first ten claims and for those claims for which claims fees have been paid.
namely claims:
- ☐ No claims fees have been paid within the prescribed time limit. The present European search report has been drawn up for the first ten claims.

X LACK OF UNITY OF INVENTION

The Search Division considers that the present European patent application does not comply with the requirement of unity of invention and relates to several inventions or groups of inventions.

namely:

1. Claims 1-4,6,8-12: Pump control involving magnetic sensing
2. Claims 1-3,5,7,13-15: Pump control involving current sensing of DC motor

- ☒ All further search fees have been paid within the fixed time limit. The present European search report has been drawn up for all claims.
- ☐ Only part of the further search fees have been paid within the fixed time limit. The present European search report has been drawn up for those parts of the European patent application which relate to the inventions in respect of which search fees have been paid.
namely claims:
- ☐ None of the further search fees has been paid within the fixed time limit. The present European search report has been drawn up for those parts of the European patent application which relate to the invention first mentioned in the claims.
namely claims:

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